



BIBLIOGRAPHY

1. Bryan, G.H., "Buckling of Plates," Proceedings of the London Mathematical Society, Vol. 22, 1891, pp. 54.
2. Dean, W.R., "The Elastic Stability of an Annular Plate," Proceedings of the Royal Society of London, England, Ser. A, Vol. 106, 1924, pp. 268.
3. Jones, R.M., Mechanics of Composite Materials, Washington, D.C., Scripta Book Co., 1975, pp. 32-153.
4. Lekhnitsky, S.G., Anisotropic Plates, 1st ed. English translation (Contributions to the Metallurgy of Steel No. 50), American Iron and Steel Institute, New York, 1956, pp. 77.
5. Majumdar, Saurindranath, "Buckling of a Thin Annular Plate under Uniform Compression," AIAA Journal, Vol. 9, September 1971, pp. 1701-1707.
6. Meissner, E., "Über das Knicken kreisringformiger Scheiben," Schweizerche Bauzeitung, Vol. 101, 1933, pp. 87-89.
7. Mossakowski, J., "Buckling of Circular Plates with Cylindrical Orthotropy," Archiwum Mechaniki Stosowanej, Vol. 12, 1960, pp. 583-596.
8. Olsson, R.G., "Über axialsymmetrische Knickung dunner Kreisringplatten," Ingenieur-Archiv, Vol. 8, 1937, pp. 449.

9. Pandalai, K.A.V. and Patel, S.A., "Buckling of Orthotropic Circular Plates," Journal of the Royal Aeronautical Society, Vol. 69, April 1965, pp. 279-280.
10. Schubert, A., 'Die Beullast dunner Kreisringplatten, die am Aussen und Innenrand gleichmassigen Druck erfahren,' Zeitschrift fur angewandte Mathematik und Mechaniki, Vol. 25/27, 1947, pp. 123-124.
11. Timoshenko, S.P. and Gere, J.M., Theory of Elastic Stability, 2nd ed., McGraw-Hill Book Co., New York, 1961, pp. 335-340.
12. Timoshenko, S.P. and Goodier, J.N., Theory of Elasticity, Asian Students'ed., Kogakusha Co., Ltd., Tokyo, 1951, pp. 146-151
13. Uthgenannt, E.B. and Brand, R.S., "Buckling of Orthotropic Annular Plates," AIAA Journal, Vol. 8, November 1970, pp. 2102-2104.
14. Vijayakumar, K. and Joga Rao, C.V., "Buckling of Polar Orthotropic Annular Plates," Journal of the Engineering Mechanics Division, ASCE, Vol. 97, June 1971, pp. 701-710
15. Vol'mir, A.S., "Flexible Plates and Shells," Translated by Department of Engineering Science and Mechanics, University of Florida, Technical Report AFFDL-TR-66-216, April 1967, pp. 40-51.
16. Willers, Fr.A., "Die Stabilitat von Kreisringplatten," Zeitschrift fur angewandte Mathematik und Mechaniki, Vol. 23, 1943 pp. 252.

17. Wiwat Klongpanich, "Buckling of Thin Annular Plates," Master's Thesis, Department of Mechanical Engineering, Graduate School, Chulalongkorn University, 1976.
18. Woinowsky-Krieger, S., "Buckling Stability of Circular Plates with Circular Cylindrical Aelotropy," Ingenieur-Archiv, Vol. 26, 1958, pp. 129-131.
19. Yamaki, N., "Buckling of Thin Annular Plate under Uniform Compression," Journal of Applied Mechanics, Transactions ASME 25E, 1958, pp. 267-273.

APPENDIX

APPENDIX A

A.1 Stress-strain Relations for Plane Stress of Orthotropic Material[3]

The stress-strain relations for orthotropic laminae can be written in matrices as

$$\begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \sigma_3 \\ \tau_{23} \\ \tau_{31} \\ \tau_{12} \end{bmatrix} = \begin{bmatrix} Q_{11} & Q_{12} & Q_{13} & 0 & 0 & 0 \\ Q_{12} & Q_{22} & Q_{23} & 0 & 0 & 0 \\ Q_{13} & Q_{23} & Q_{33} & 0 & 0 & 0 \\ 0 & 0 & 0 & Q_{44} & 0 & 0 \\ 0 & 0 & 0 & 0 & Q_{55} & 0 \\ 0 & 0 & 0 & 0 & 0 & Q_{66} \end{bmatrix} \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \\ \gamma_{23} \\ \gamma_{31} \\ \gamma_{12} \end{bmatrix} \quad (A.1)$$

A plane stress state is defined by

$$\sigma_3 = 0, \quad \tau_{23} = 0, \quad \tau_{31} = 0$$

Therefore, the stress-strain relations above is reduced for plane stress as

$$\begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \tau_{12} \end{bmatrix} = \begin{bmatrix} Q_{11} & Q_{12} & 0 \\ Q_{12} & Q_{22} & 0 \\ 0 & 0 & Q_{66} \end{bmatrix} \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \gamma_{12} \end{bmatrix} \quad (A.2)$$

where the Q_{ij} , the so-called reduced stiffness, may be written in terms of the engineering constants as

$$\begin{aligned}
 Q_{11} &= \frac{E_1}{1 - \nu_{12}\nu_{21}} \\
 Q_{12} &= \frac{\nu_{12}E_2}{1 - \nu_{12}\nu_{21}} = \frac{\nu_{21}E_1}{1 - \nu_{12}\nu_{21}} \\
 Q_{22} &= \frac{E_2}{1 - \nu_{12}\nu_{21}} \\
 Q_{66} &= G_{12}
 \end{aligned} \tag{A.3}$$

The Poisson's ratio, $\nu_{ij} = -\epsilon_j/\epsilon_i$, is for transverse strain in the j -direction when stressed in the i -direction.

A.2 Resultant Moments for Orthotropic Material [3]

The implications of the Kirchhoff or the Kirchhoff-Love hypothesis on the laminate displacements u , v , and w in the x -, y -, and z -directions being that the displacement, u , at any point z through the laminate thickness is

$$u = u_o - zw_{,x} \tag{A.4}$$

where u_o is the displacement of a point on the reference plane in the x -direction.

By similar reasoning, the displacement, v , in the y -direction is

$$v = v_o - zw_{,y} \tag{A.5}$$

For small strains (linear elasticity), the strains are defined in terms of displacements as

$$\epsilon_1 = \epsilon_{xx} = u_{,x} = -zw_{,xx}$$

$$\epsilon_2 = \epsilon_{yy} = v_{,y} = -zw_{,yy} \quad (A.6)$$

$$\gamma_{12} = \gamma_{xy} = u_{,y} + v_{,x} = -2zw_{,xy}$$

From Eq.(A.2), stresses, in terms of displacements, are

$$\begin{aligned}\sigma_1 &= \sigma_{xx} = Q_{11}\epsilon_1 + Q_{12}\epsilon_2 = -\frac{zE_1}{1 - \nu_{12}\nu_{21}} (w_{,xx} + \nu_{21}w_{,yy}) \\ \sigma_2 &= \sigma_{yy} = Q_{12}\epsilon_1 + Q_{22}\epsilon_2 = -\frac{zE_2}{1 - \nu_{12}\nu_{21}} (w_{,yy} + \nu_{12}w_{,xx})\end{aligned} \quad (A.7)$$

$$\tau_{12} = \tau_{xy} = G_{12}\gamma_{12} = -2G_{12}zw_{,xy}$$

The moment resultants acting on a laminate are obtained by integration of the stresses in each layer or lamina through the laminate thickness,

$$\begin{bmatrix} M_{xx} \\ M_{yy} \\ M_{xy} \end{bmatrix} = \int_{-h/2}^{h/2} \begin{bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \tau_{xy} \end{bmatrix} \cdot zdz \quad (A.8)$$

That is,

$$\begin{aligned}M_{xx} &= \int_{-h/2}^{h/2} \sigma_{xx} zdz \\ &= - \int_{-h/2}^{h/2} \frac{z^2 E_1}{1 - \nu_{12}\nu_{21}} (w_{,xx} + \nu_{21}w_{,yy}) dz \\ &= - \frac{E_1 h^3}{12(1 - \nu_{12}\nu_{21})} (w_{,xx} + \nu_{21}w_{,yy}) \\ &= - D_x (w_{,xx} + \nu_{21}w_{,yy})\end{aligned}$$

Similarly,

$$M_{yy} = - D_y (w_{yy} + \nu_{12} w_{xx})$$

$$M_{xy} = - D_{xy} w_{xy}$$

$$\text{where } D_x = \frac{E_1 h^3}{12(1 - \nu_{12} \nu_{21})}$$

$$D_y = \frac{E_2 h^3}{12(1 - \nu_{12} \nu_{21})}$$

$$D_{xy} = \frac{G_{12} h^3}{6}$$

Therefore,

$$\sigma_{xx} = - \frac{12z}{h^3} (D_x w_{xx} + D_y w_{yy})$$

$$\sigma_{yy} = - \frac{12z}{h^3} (D_y w_{yy} + D_x w_{xx}) \quad (A.9)$$

$$\tau_{xy} = - \frac{12z}{h^3} D_{xy} w_{xy}$$

APPENDIX B

GALERKIN'S METHOD [15]

This method was developed by I.G. Bubnov and applied by B.G. Galerkin for the series solution of some problems of engineering mechanics. Consider the variation of the following equation,

$$\iint_A L \cdot \delta w \cdot dx \cdot dy = 0 \quad (B.1)$$

in which the quantity L is the expression in term of w and their derivatives. The most effective way to integrate the fundamental differential equations of the theory of flexible plates is to represent the deflection $w(x,y)$ in the form of a series

$$w = c_1 \eta_1 + c_2 \eta_2 + \dots + c_n \eta_n = \sum_{i=1}^n c_i \eta_i \quad (B.2)$$

where η_i are the selected quantities, independent of each other and are functions of the coordinates x and y , c_i are some parametric quantities to be determined.

Making use of expression (B.2), δw is expressed in terms of the variation of the parameters c_i

$$\delta w = \sum_{i=1}^n \eta_i \delta c_i \quad (B.3)$$

Substitute series (B.3) into expression (B.1), then

$$\sum_{i=1}^n \int_A \int L \cdot \eta_i \delta c_i \cdot dx \cdot dy = 0 \quad (B.4)$$

But the variations δc_i are arbitrary, consequently, equation (B.4) is satisfied if each equation of the following type is separately satisfied

$$\int_A \int L \cdot \eta_i \cdot dx \cdot dy = 0 ; i = 1, 2, \dots, n \quad (B.5)$$

After integration with respect to x and y we obtain a set of algebraic equations containing the unknown parameters c_i . The number of these equations is equal to n . Solving this system of equations, the parameters c_i are found. In buckling problem, L is the buckling equation and the determination of c_i is indeterminate which results in a set of equations whose eigen value is the critical buckling load.

APPENDIX C

Appendix C. shows the flow chart and the computer program used in the computations where

$$UN = v_*$$

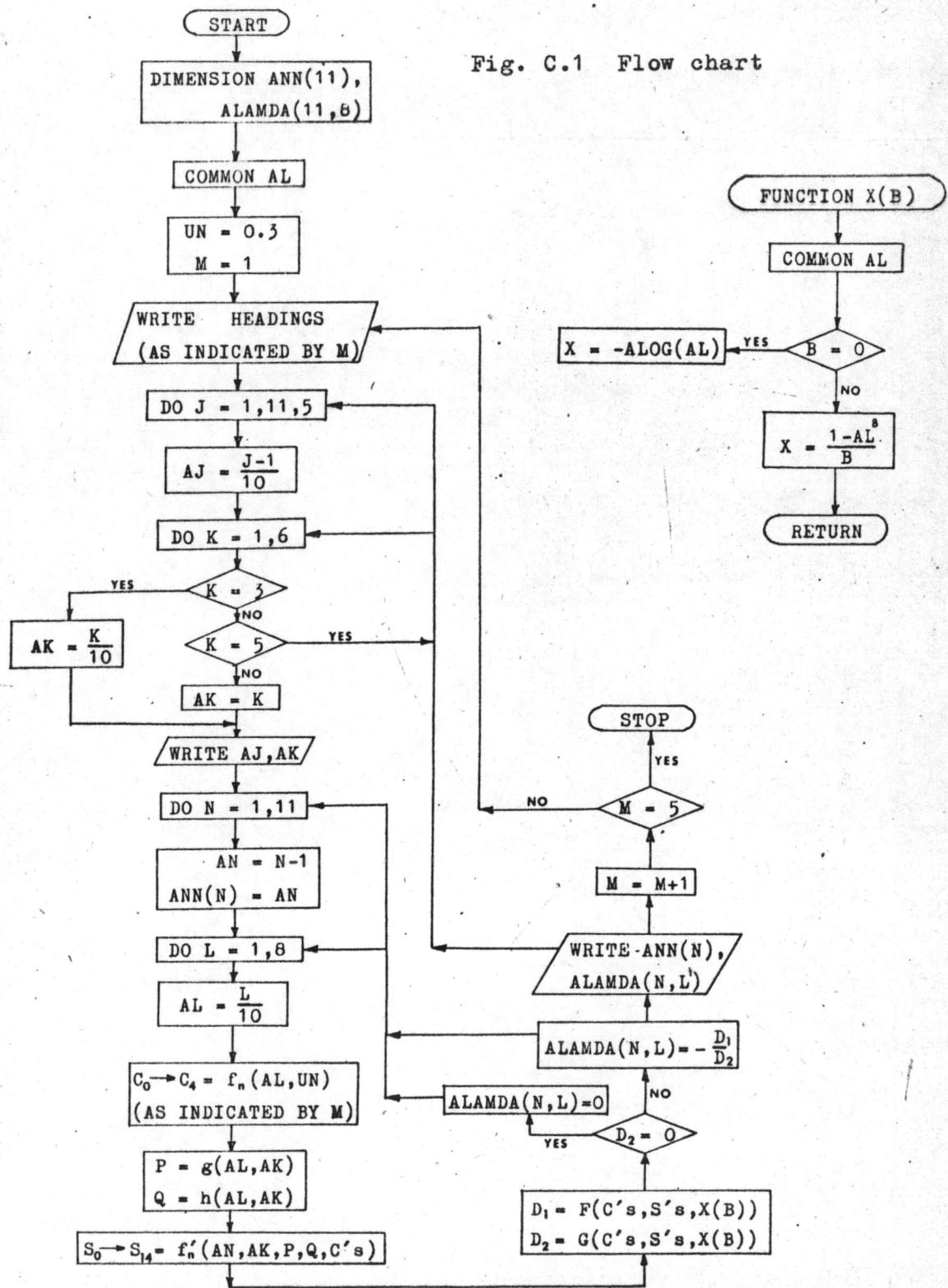
$$AN = n$$

$$AK = k$$

$$AJ = \beta$$

$$AL = \alpha$$

$$\text{ALAMDA}(N,L) = \lambda(n, \alpha)$$



C 3015583 ATHIKOM BANGVIWAT
 C TO FIND THE CRITICAL LOADS FOR UNSYMMETRIC BUCKLING PLATES.
 DIMENSION ANN(11),ALAMDA(11,8)
 COMMON AL
 UN = 0.3
 M = 1
 100 WRITE(3,250)
 GO TO 140
 110 WRITE(3,260)
 GO TO 140
 120 WRITE(3,270)
 GO TO 140
 130 WRITE(3,280)
 140 DO 240 J=1,11,5
 AJ = J
 AJ = (AJ-1.)/10.
 DO 240 K=1,6
 IF(K.EQ.3) GO TO 150
 IF(K.EQ.5) GO TO 240
 AK = K
 GO TO 160
 150 AK=K
 AK = AK/10.
 160 WRITE(3,290) AJ, AK
 DO 230 N=1,11
 AN = N
 AN = AN-1.
 ANN(N) = AN
 DO 230 L=1,8
 AL = L
 AL = AL/10.
 GO TO (170,180,190,200),M
 170 CO = 1.
 C1 = -CO*2.*((AL**8-2.*AL**6+2.*AL**2-1.)/(AL**8-3.*AL**6
 * +3.*AL**4-AL**2))
 C2 = -CO*(3.*AL**8-4.*AL**6+1.)/(AL**8-2.*AL**6+AL**4)-C
 * 1*(2.*AL**6-3.*AL**4+1.)/(AL**6-2.*AL**4+AL**2)
 C3 = -CO*(AL**8-1.)/(AL**8-AL**6)-C1*(AL**6-1.)/(AL**6-A
 * L**4)-C2*(AL**4-1.)/(AL**4-AL**2)
 C4 = -CO-C1-C2-C3
 GO TO 210
 180 CO = 1.
 C1 = -CO*2.*((13.+UN)*AL**10-(33.+3.*UN)*AL**8+(18.+2.*U
 * N)*AL**6+(14.+2.*UN)*AL**4-(15.+3.*UN)*AL**2+(3.+UN
 *))/((13.+UN)*AL**10-(44.+4.*UN)*AL**8+(54.+6.*UN)*A
 * L**6-(28.+4.*UN)*AL**4+(5.+UN)*AL**2)
 C2 = -CO*(3.*AL**8-4.*AL**6+1.)/(AL**8-2.*AL**6+AL**4)-C
 * 1*(2.*AL**6-3.*AL**4+1.)/(AL**6-2.*AL**4+AL**2)
 C3 = -CO*(AL**8-1.)/(AL**8-AL**6)-C1*(AL**6-1.)/(AL**6-A
 * L**4)-C2*(AL**4-1.)/(AL**4-AL**2)
 C4 = -CO-C1-C2-C3
 GO TO 210
 190 CO = 1.
 C1 = -CO*2.*((3.+UN)*AL**10-(15.+3.*UN)*AL**8+(14.+2.*UN

```

* ) * AL ** 6 + ( 18 . + 2 . * UN ) * AL ** 4 - ( 33 . + 3 . * UN ) * AL ** 2 + ( 13 . + UN
* )) / ( ( 5 . + UN ) * AL ** 10 - ( 28 . + 4 . * UN ) * AL ** 8 + ( 54 . + 6 . * UN ) * AL
* * * 6 - ( 44 . + 4 . * UN ) * AL ** 4 + ( 13 . + UN ) * AL ** 2 )
C2 = - CC * ( AL ** 8 - 4 . * AL ** 2 + 3 . ) / ( AL ** 8 - 2 . * AL ** 6 + AL ** 4 ) - C1 *
* AL ** 6 - 3 . * AL ** 2 + 2 . ) / ( AL ** 6 - 2 . * AL ** 4 + AL ** 2 )
C3 = - CC * ( AL ** 8 - 1 . ) / ( AL ** 8 - AL ** 6 ) - C1 * ( AL ** 6 - 1 . ) / ( AL ** 6 - A
* L ** 4 ) - C2 * ( AL ** 4 - 1 . ) / ( AL ** 4 - AL ** 2 )
C4 = - CC - C1 - C2 - C3 ,
GO TO 210
C0 = 1 .
C1 = - CC * 2 . * ( ( 35 . + 16 . * UN + UN ** 2 ) * AL ** 10 - ( 165 . + 48 . * UN + 3 . * U
* N ** 2 ) * AL ** 8 + ( 126 . + 32 . * UN + 2 . * UN ** 2 ) * AL ** 6 + ( 126 . + 32 . *
* UN + 2 . * UN ** 2 ) * AL ** 4 - ( 165 . + 48 . * UN + 3 . * UN ** 2 ) * AL ** 2 + ( 39
* . + 16 . * UN + UN ** 2 ) ) / ( ( 65 . + 18 . * UN + UN ** 2 ) * AL ** 10 - ( 308 . + 7
* 2 . * UN + 4 . * UN ** 2 ) * AL ** 8 + ( 486 . + 108 . * UN + 6 . * UN ** 2 ) * AL ** 6
* - ( 308 . + 72 . * UN + 4 . * UN ** 2 ) * AL ** 4 + ( 65 . + 18 . * UN + UN ** 2 ) * AL
* ** 2 )
C2 = - CC * ( ( 15 . + 3 . * UN ) * AL ** 8 - ( 28 . + 4 . * UN ) * AL ** 6 + ( 13 . + UN ) ) /
* ( ( 5 . + UN ) * AL ** 8 - ( 22 . + 2 . * UN ) * AL ** 6 + ( 13 . + UN ) * AL ** 4 ) - C1
* * ( ( 14 . + 2 . * UN ) * AL ** 6 - ( 27 . + 3 . * UN ) * AL ** 4 + ( 13 . + UN ) ) / ( ( 9
* . + UN ) * AL ** 6 - ( 22 . + 2 . * UN ) * AL ** 4 + ( 13 . + UN ) * AL ** 2 )
C3 = - CC * ( AL ** 8 - 1 . ) / ( AL ** 8 - AL ** 6 ) - C1 * ( AL ** 6 - 1 . ) / ( AL ** 6 - A
* L ** 4 ) - C2 * ( AL ** 4 - 1 . ) / ( AL ** 4 - AL ** 2 )
C4 = - CC - C1 - C2 - C3
P = - ( 1 . - AJ * AL ** ( AK + 1 . ) ) / ( 1 . - AL ** ( 2 . * AK ) )
Q = AL ** ( AK + 1 . ) * ( AL ** ( AK - 1 . ) - AJ ) / ( 1 . - AL ** ( 2 . * AK ) )
S0 = - CC * ( 2 . * AN ** 2 + 2 . * AN ** 2 * AK ** 2 - AN ** 4 * AK ** 2 )
S1 = - C1 * ( 2 . * AN ** 2 + 2 . * AN ** 2 * AK ** 2 - AN ** 4 * AK ** 2 )
S2 = C2 * ( 72 . - 8 . * AK ** 2 - 18 . * AN ** 2 - 2 . * AN ** 2 * AK ** 2 + AN ** 4 * AK *
* * 2 )
S3 = C3 * ( 600 . - 24 . * AK ** 2 - 50 . * AN ** 2 - 2 . * AN ** 2 * AK ** 2 + AN ** 4 * A
* K ** 2 )
S4 = C4 * ( 2352 . - 48 . * AK ** 2 - 98 . * AN ** 2 - 2 . * AN ** 2 * AK ** 2 + AN ** 4 *
* AK ** 2 )
S5 = CC * AN ** 2 * AK * P
S6 = - C0 * AN ** 2 * AK * Q
S7 = C1 * ( AN ** 2 * AK - 2 . * AK - 2 . ) * P
S8 = - C1 * ( AN ** 2 * AK - 2 . * AK + 2 . ) * Q
S9 = C2 * ( AN ** 2 * AK - 4 . * AK - 12 . ) * P
S10 = - C2 * ( AN ** 2 * AK - 4 . * AK + 12 . ) * Q
S11 = C3 * ( AN ** 2 * AK - 6 . * AK - 30 . ) * P
S12 = - C3 * ( AN ** 2 * AK - 6 . * AK + 30 . ) * Q
S13 = C4 * ( AN ** 2 * AK - 8 . * AK - 56 . ) * P
S14 = - C4 * ( AN ** 2 * AK - 8 . * AK + 56 . ) * Q
D1 = S0 * CC * X( - 3 . ) + ( S1 * C0 + S0 * C1 ) * X( - 1 . ) + ( S2 * C0 + S1 * C1 + S0 * C
* 2 ) * X( 1 . ) + ( S3 * CC + S2 * C1 + S1 * C2 + S0 * C3 ) * X( 3 . ) + ( S4 * C0 + S3 * C
* C1 + S2 * C2 + S1 * C3 + S0 * C4 ) * X( 5 . ) + ( S4 * C1 + S3 * C2 + S2 * C3 + S1 * C
* 4 ) * X( 7 . ) + ( S4 * C2 + S3 * C3 + S2 * C4 ) * X( 9 . ) + ( S4 * C3 + S3 * C4 ) * X(
* 11 . ) + S4 * C4 * X( 13 . )
D2 = S5 * C0 * X( AK - 2 . ) + S6 * C0 * X( - AK - 2 . ) + ( S7 * C0 + S5 * C1 ) * X( AK ) +
* ( S8 * C0 + S6 * C1 ) * X( - AK ) + ( S9 * C0 + S7 * C1 + S5 * C2 ) * X( AK + 2 . ) + (
* S10 * C0 + S8 * C1 + S6 * C2 ) * X( - AK + 2 . ) + ( S11 * C0 + S9 * C1 + S7 * C2 + S
* 5 * C3 ) * X( AK + 4 . ) + ( S12 * C0 + S10 * C1 + S8 * C2 + S6 * C3 ) * X( - AK + 4 .
* ) + ( S13 * C0 + S11 * C1 + S9 * C2 + S7 * C3 + S5 * C4 ) * X( AK + 6 . ) + ( S14 * C

```

```

*   0+S12*C1+S10*C2+S8*C3+S6*C4)*X(-AK+6.)+(S13*C1+S11*
*   C2+S9*C3+S7*C4)*X(AK+8.)+(S14*C1+S12*C2+S10*C3+S8*C
*   4)*X(-AK+8.)+(S13*C2+S11*C3+S9*C4)*X(AK+10.)+(S14*C
*   2+S12*C3+S10*C4)*X(-AK+10.)+(S13*C3+S11*C4)*X(AK+12
*   .)+(S14*C3+S12*C4)*X(-AK+12.)+S13*C4*X(AK+14.)+S14*
*   C4*X(-AK+14.)
1F(D2.EQ.0.) GO TO 220
ALAMDA(N,L)=-D1/D2
GO TO 230
220 ALAMDA(N,L) = 0.
230 CONTINUE
      WRITE(3,300)
      WRITE(3,310) (ANN(N),(ALAMDA(N,L),L=1,8),N=1,11)
240 CONTINUE
      M = M+1
      IF(M.EQ.5) STOP
      GO TO (100,110,120,130),M
250 FORMAT(//40X,'CRITICAL LOADS FOR UNSYMMETRIC BUCKLING',//,
*40X,'OF PCLAR ORTHOTROPIC ANNULAR PLATES.',//20X,'CASE',
*' : BOTH EDGES ARE CLAMPED.',//)
260 FORMAT(//40X,'CRITICAL LOADS FOR UNSYMMETRIC BUCKLING',//,
*40X,'OF PCLAR ORTHOTROPIC ANNULAR PLATES.',//20X,'CASE',
*' : INNER EDGE IS SIMPLY SUPPORTED',/27X,'CUTER EDGE IS',
*'S CLAMPED.',//)
270 FORMAT(//40X,'CRITICAL LOADS FOR UNSYMMETRIC BUCKLING',//,
*40X,'OF PCLAR ORTHOTROPIC ANNULAR PLATES.',//20X,'CASE',
*' : INNER EDGE IS CLAMPED',/27X,'CUTER EDGE IS SIMPLY ',
*' SUPPORTED.',//)
280 FORMAT(//40X,'CRITICAL LOADS FOR UNSYMMETRIC BUCKLING',//,
*40X,'OF PCLAR ORTHOTROPIC ANNULAR PLATES.',//20X,'CASE',
*' : BOTH EDGES ARE SIMPLY SUPPORTED.',//)
290 FORMAT(////28X,'PRESSURE RATIO : PI/PO = ',F5.1,/28X,
*'RIGIDITY RATIO : K = ',F5.1,/)
300 FORMAT(42X,'LAMDA : CRITICAL LOAD PARAMETER',/16X,'#',
*42X,'A/B',/12X,'N',3X,'*',7X,'0.1',8X,'0.2',8X,'0.3',8X,
*'0.4',8X,'0.5',8X,'0.6',8X,'0.7',8X,'0.8',/10X,49('* '))
310 FORMAT(10X,F4.0,2X,'*',1X,8F11.1)
      STOP
      END

```

C FUNCTION SUBPROGRAM

FUNCTION X(B)

COMMON AL

IF(B) 320,330,320

320 X = (1.-AL**B)/B

RETURN

330 X = -ALCG(AL)

RETURN

END

AUTOBIOGRAPHY

Mr. Athikom Bangviwat, born on Nov. 15, 1954, in Bangkok, Thailand, finished his pre-university studies at Trium Udom Secondary School. Intending for the engineering, he pursued in the Department of Mechanical Engineering, Chulalongkorn University where he received, in the first year, an honour certificate for good study record in 1974. Having formally completed the B.Eng. in 1977, he was further enrolled in the master degree program.

