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ภาคผนวก

ภาคผนวก ก.

โมเดลระบบ LFC ของระบบไฟฟ้ากำลังสองเขตที่เชื่อมโยงกัน

โมเดลระบบ LFC ของระบบไฟฟ้ากำลังสองเขตที่ใช้ในวิทยานิพนธ์ฉบับนี้ตลอดจนในงานวิจัยของ Calovic (1972, 1973, 1977) แต่ละเขตประกอบด้วยหน่วยผลิตพลังน้ำหนึ่งหน่วย และหน่วยผลิตพลังไอน้ำหนึ่งหน่วย หน่วยผลิตพลังไอน้ำใช้เครื่องจักรพลังไอน้ำแบบ reheat ซึ่งแสดงไว้ในรูปที่ ก.1 กัปเวอร์เนอร์ที่ใช้กับเครื่องจักรพลังไอน้ำดังกล่าวเป็นแบบ accelerotachometric ซึ่งแสดงไว้ในรูปที่ 2.4 ส่วนหน่วยผลิตพลังน้ำเป็นโรงจักรพลังน้ำที่มีเขื่อนกักเก็บน้ำดังแสดงไว้ในรูปที่ ก.2 กัปเวอร์เนอร์ที่ใช้คู่กันเป็นแบบ transient speed-droop ซึ่งแสดงไว้ในรูปที่ 2.5 ดังนั้นระบบไฟฟ้ากำลังแต่ละเขตจึงเป็นโรงจักรผสมระหว่างพลังน้ำและพลังไอน้ำ เหตุผลที่เลือกโมเดลของหน่วยผลิตแต่ละหน่วยเป็นชนิดดังกล่าวคือ โรงจักรทั้งสองแบบเป็นที่นิยมใช้กันทั่วไปในระบบไฟฟ้ากำลัง รายละเอียดของโมเดลตลอดจนสมการสถานะของส่วนประกอบต่าง ๆ ในระบบไฟฟ้ากำลังอาทิเช่น กัปเวอร์เนอร์, เทอร์ไบน์, เครื่องกำเนิดไฟฟ้า เป็นต้น ค้นหาได้จาก Calovic (1971)

ภายใต้สมมติฐานของพลวัตเนื่องจากสัญญาณขนาดเล็ก โมเดลของระบบไฟฟ้ากำลังสองเขตที่เชื่อมโยงกันด้วยเส้นเชื่อมต่อสำหรับใช้อธิบายพฤติกรรมของระบบระหว่างกำลังจริงกับความถี่สามารถถูกทำให้เป็นเชิงเส้นรอบจุดทำงานปกติ ตัวแปรของระบบต่าง ๆ ที่ใช้เป็นตัวแปรอินครีเมนทัล (incremental variable) ทั้งสิ้นและในขั้นตัวแปรทุกตัวใช้หน่วยเป็นเปอร์เซ็นต์ทั้งสิ้น โมเดลดังกล่าวเขียนได้เป็น

$$\dot{x}(t) = Ax(t) + Bu(t) + Ez(t) \quad (ก.1)$$

โดยที่ $x(t) = [x_1^T(t), \Delta P_{12}, x_2^T(t)]^T$ เป็นสถานะของระบบทั้งหมดมิติ 17

$$x_i(t) = [\Delta a_i, \Delta p_{t1}, \Delta p_{t2}, \Delta p_{t3}, \Delta a_H, \Delta q, \Delta f]_i^T, \quad i=1,2$$

เป็นสถานะของระบบไฟฟ้าแต่ละเขตมิติ 8

$\Delta P_{12}(t)$ เป็นการเบี่ยงเบนของกำลังจริงในเส้นเชื่อมต่อ

$$u(t) = [\Delta f_{mT1}, \Delta f_{mH1}, \Delta f_{mT2}, \Delta f_{mH2}]^T$$

เป็นเวกเตอร์ควบคุมของหน่วยผลิตทั้งหมดมิติ 4

$$z(t) = [\Delta PL_1, \Delta PL_2]^T$$

เป็นเวกเตอร์การเปลี่ยนแปลงของโหลดตีมานด์ทั้งหมดมิติ 2

ตัวแปรในสมการ (ก.1) เป็นตัวแปรอินทรีย์เมนทัลซึ่งมีหน่วยเป็นเปอร์เซ็นต์ทั้งหมดโดยมีคำอธิบายดังในตารางที่ ก.1 ในแต่ละเขตหน่วยผลิตทั้งหมดถูกควบคุมด้วยตัวควบคุมเขตของตัวเองตามหลักการของการควบคุมร่วมกันในเขต (area-control concept) จำนวนตัวแปรควบคุมของระบบทั้งหมดในสมการ (ก.1) ลดลงมาเหลือเท่ากับจำนวนของเขตทั้งหมด ตัวควบคุมของเขตอธิบายได้ด้วยสมการ

$$u(t) = \sqrt{w(t)} \quad (\text{ก.2})$$

โดยที่ $w(t) = [w_1(t), w_2(t)]^T$ เป็นเวกเตอร์ควบคุมของเขตทั้งหมด มิติ 2

$\sqrt{\quad}$ เป็นเมตริกซ์ของการปรับส่วนในการควบคุม มิติ 4×2

เมื่อในระบบมีการสื่อนิติกรัลของ ACE สถานะของระบบที่เพิ่มขึ้นได้แก่

$$\dot{v}(t) = ACE = Dx(t) \quad (\text{ก.3})$$

โดยที่ $v(t) = [v_1, v_2]^T$ เป็นเวกเตอร์อินทิกรัลของ ACE มิติ 2

ระบบไฟฟ้ากำลังแต่ละเขตมีการวัดดังนี้

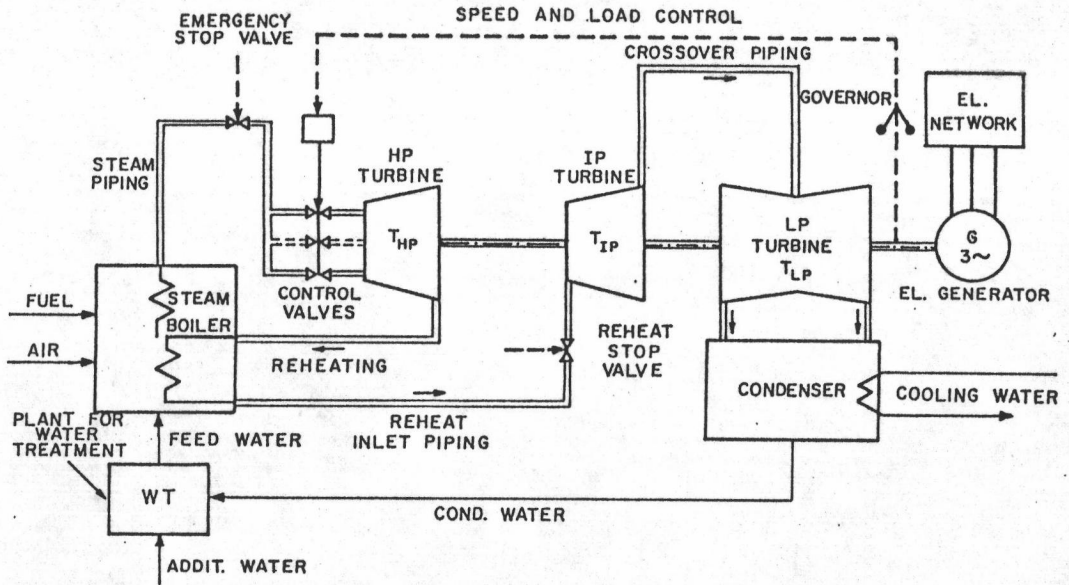
$$y^i = C^i x \quad (\text{ก.4})$$

โดยที่ $y^i = [\Delta P_{Ti}, \Delta P_{Hi}, \Delta f_i, \Delta P_{12}, v_i]^T$

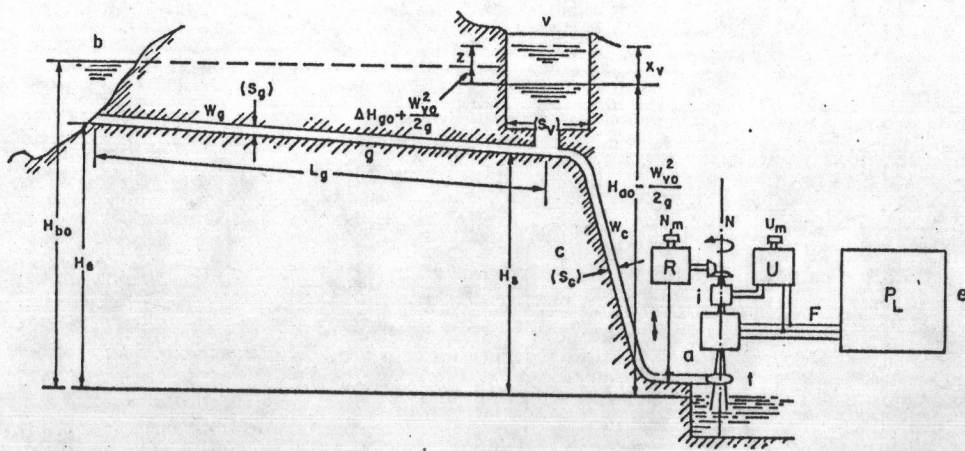
P_{Ti} เป็นอินทรีย์เมนทัลหรือการเบี่ยงเบนของกำลังขาออกของเทอร์ไบน์พลังไอน้ำในเขตที่ i

P_{Hi} เป็นอินทรีย์เมนทัลหรือการเบี่ยงเบนของกำลังขาออกของเทอร์ไบน์พลังน้ำในเขตที่ i

เมตริกซ์ต่าง ๆ ในสมการ (ก.1)-(ก.4) ตลอดจนค่าตัวเลขต่าง ๆ แสดงไว้ในรูปที่ ก.3



รูปที่ ก.1 โรงจักรพลังไอน้ำแบบ reheat



Legend:

- a - Generator
- b - Storage Reservoir
- c - Penstock
- e - El. Network
- g - Intake Tunnel
- v - Surge-Tank
- R - Turbine Governor
- t - Hydraulic Turbine
- i - Exciter
- u - Voltage Regulator

รูปที่ ก.2 โรงจักรพลังน้ำแบบเขื่อนกักเก็บน้ำ

$$A = \begin{bmatrix} A_1 & a_{12} & 0 \\ m & 0 & -m \\ 0 & -\alpha a_{21} & A_2 \end{bmatrix}, \quad B = \begin{bmatrix} B_1 & 0 \\ 0 & 0 \\ 0 & B_2 \end{bmatrix},$$

$$E = \begin{bmatrix} E_1 & 0 \\ 0 & 0 \\ 0 & E_2 \end{bmatrix}, \quad D = \begin{bmatrix} D_1 & 1 & 0 \\ 0 & -\alpha & D_2 \end{bmatrix},$$

$$C^1 = \begin{bmatrix} C & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix}, \quad C^2 = \begin{bmatrix} C & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix},$$

$$A_1 = \begin{bmatrix} -0.2 & & & & & & & & -4.0 \\ & 4.75 & -5.0 & & & & & & \\ & & 0.1667 & -0.1667 & & & & & \\ & & & 2.0 & -2.0 & & & & \\ & -0.08 & -0.0747 & -0.112 & -3.9944 & 10.0 & -0.928 & -9.1011 & \\ & & & & 0.2 & -0.50 & & & \\ & & & & & 1.3194 & -1.3889 & -0.2778 & \\ 0.01 & 0.0093 & 0.014 & -0.0632 & & & 0.1160 & -0.1124 & \end{bmatrix}$$

$$A_2 = \begin{bmatrix} -0.2 & & & & & & & & -4.0 \\ & 4.75 & -5.0 & & & & & & \\ & & 0.1667 & -0.1667 & & & & & \\ & & & 2.0 & -2.0 & & & & \\ & -0.10 & -0.0933 & -0.14 & -4.096 & 10.0 & -0.7422 & -9.1079 & \\ & & & & 0.2 & -0.50 & & & \\ & & & & & 1.3194 & -1.3889 & -0.2778 & \\ 0.0125 & 0.0117 & 0.0175 & -0.0506 & & & 0.0928 & -0.1115 & \end{bmatrix}$$

$$B_1 = B_2 = \begin{bmatrix} 4 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 10 & 0 & 0 & 0 & 0 \end{bmatrix}^T$$

$$C = \begin{bmatrix} 0 & 0.30 & 0.28 & 0.42 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1.52 & 0 & 2.78 & 0.217 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$E_1 = E_2 = \begin{bmatrix} 0 & 0 & 0 & 0 & 0.6667 & 0 & 0 & 0 & -0.8333 \end{bmatrix}^T$$

$$D_1 = D_2 = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 10 \end{bmatrix}$$

$$m = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 22.2144 \end{bmatrix}$$

$$\sim = \begin{bmatrix} 0.4 & 0.6 & 0 & 0 \\ 0 & 0 & 0.5 & 0.5 \end{bmatrix}^T$$

$$a_{21} = a_{12} = E_1 = E_2, \quad \alpha = 1.0$$

รูปที่ ก.3 แสดงค่าของเมตริกซ์ต่าง ๆ ของโมเดลระบบ LFC

symbol	description
Δa_T	the incremental steam turbine valve opening in p.u.
Δp_{T1}	the incremental high-pressure output of steam turbine in p.u.
Δp_{T2}	the incremental intermediate-pressure output of steam turbine in p.u.
Δp_{T3}	the incremental low-pressure output of steam turbine in p.u.
Δa_H	the incremental hydroturbine gate opening in p.u.
Δv	the incremental dashpot piston position relative to the lever of permanent speed droop of hydroturbine governor in p.u.
Δq	the incremental hydroturbine flow in p.u.
Δf	the frequency deviation in p.u.
ΔP_{12}	the incremental tie-line power flow in p.u.
Δf_{mT}	the incremental steam unit control input in p.u.
Δf_{mH}	the incremental hydrounit control input in p.u.
ΔP_L	the incremental area-load demand or area-load disturbance in p.u.

ตารางที่ ก.1 อธิบายสัญลักษณ์ของตัวแปรต่าง ๆ ในโมเดลของระบบ LFC

ภาคผนวก ข

เอกลักษณ์สำคัญที่เกี่ยวกับผลบวกเฉียงของเมตริกซ์

จากในบทที่ 2 และบทที่ 5 ของวิทยานิพนธ์ฉบับนี้ เห็นได้ว่า การหาเงื่อนไขจำเป็นสำหรับคำตอบของการป้อนกลับสัญญาณแบบเล็ง เลิศ และแบบ Stackelberg เกี่ยวกับการหาอนุพันธ์ (derivative) ของฟังก์ชันจำนวนจริงเทียบกับเมตริกซ์ตลอดเวลา และฟังก์ชันจำนวนจริงดังกล่าวมีรูปแบบเฉพาะ คือ อยู่ในรูปผลบวกเฉียง (trace) ของฟังก์ชันเมตริกซ์ ดังนั้นในที่นี้จะแสดงเอกลักษณ์ที่จำเป็นเกี่ยวกับผลบวกเฉียงของเมตริกซ์ และอนุพันธ์ของฟังก์ชันดังกล่าวเทียบกับเมตริกซ์ สำหรับรายละเอียดและขั้นตอนการพิสูจน์หาได้ใน Athans and Schweppe (1965), Athans (1967), Ermer (1972) และ Walsh (1977)

กำหนดให้ $f = f(X)$ และ $g = g(X)$ เป็นฟังก์ชันค่าเมตริกซ์จัตุรัส ดังนั้น $\text{tr} [f(X)]$ จึงเป็นจำนวนจริง X และ Y เป็นเมตริกซ์จำนวนจริงมิติ $n \times m$ และ $m \times n$ ตามลำดับ N และ L เป็นเมตริกซ์จำนวนจริงมิติ $n \times n$ และ $m \times m$ ตามลำดับ เอกลักษณ์ดังกล่าวได้แก่

- 1) $\text{tr} (N) = \text{tr} (N^T)$
- 2) $\text{tr} (NL) = \text{tr} (LN)$
- 3) $\frac{d}{dX} \text{tr} f(X) = \left[\frac{d}{dx} \text{tr} f(X) \right]_{n \times m}$
- 4) $\frac{d}{dX} \text{tr} (NX) = N^T$
- 5) $\frac{d}{dX} \text{tr} (NX^T) = N$
- 6) $\frac{d}{dX} \text{tr} (NXL) = N^T L^T$
- 7) $\frac{d}{dX} \text{tr} (NXLX^T) = N^T XL^T + NXL$
- 8) $\frac{d}{dX} \text{tr} [f(X)g(X)] = \frac{d}{dX} \text{tr} [f(X)g^c(X)] + \frac{d}{dX} \text{tr} [f^c(X)g(X)]$

where the superscript "c" means that the term is held constant and does not undergo the differentiation operation.

ภาคผนวก ค

โปรแกรมที่ใช้

User: EEEB815818

-at PRO

<STUD>THESIS>EEEE815818>LINPAKDIR>STKOUT.F77


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Label: PRTO02 -form

Pathname: <STUD>THESIS>EEEE815818>LINPAKDIR>STKOUT.F77
File last modified: 88-04-12.18:58:12. Tue

Spooled: 88-04-12.18:58:24. Tue [Spooler rev 19.4]
Started: 88-04-12.18:59:40. Tue on: PRO by: PRO

C PROGRAMME LISTING WRITTEN BY SUCHIN ARUNSAWATWONG, 12 MARCH 1988.

C PROGRAMME LISTING WRITTEN BY SUCHIN ARUNSAWATWONG, 12 MARCH 1988.

C-----
 C M. Eng THESIS TITLED
 C "DECENTRALIZED LOAD-FREQUENCY CONTROL OF 2-AREA
 C POWER SYSTEMS VIA OUTPUT FEEDBACK"
 C-----

```

PROGRAM MAIN
IMPLICIT INTEGER*2 (I-N)
REAL*4  A(17, 17), B(17, 4), F(17, 2), D(2, 17), KP(2, 17), KI(2, 2),
&      R(2, 2), NU(4, 2), A1(19, 19), B1(19, 2),
&      BNU(17, 2), F1(19, 2), XO(19),
&      DT
REAL*4  AC(19, 19), GRAD1(5), GRAD2(5), FF1(5), FF2(5), G1(5, 19)
&      , C2(5, 19)
REAL*4  U1(361), U2(361), U3(361), RR(19), RI(19)
C      REAL*4  U1(361), U2(361), U3(361), RR(19), RI(19), Q(19, 19)
INTEGER*2  N, L, M, K, IND, IPOINT
INTEGER*4  INN
REAL*8  EPS, DFX
REAL*8  DA(19, 19), DB(19, 2), DC1(5, 19), DC2(5, 19), R1, R2
C      REAL*8  DA(19, 19), DB(19, 2), DC1(5, 19), DC2(5, 19), DG(19, 19), R1, R2
REAL*8  DAC(19, 19), KO(19, 19), K1(19, 19), L1(19, 19), DF1(5), DF2(5)
REAL*8  DGRAD1(5), DGRAD2(5), J1, J2, Q1(19, 19), Q2(19, 19)
REAL*8  C13(3, 19), C23(3, 19)
INTEGER*2  LIMIT, IN, IM1, IM2, IR1, IR2, IR13, IR23

C      IND = 1
      N=17
      M=4
      K=2
      L=2

C      IN = 19
      IM1 = 1
      IM2 = 1
      IR13 = 3
      IR23 = 3
      IR1 = 5
      IR2 = 5

C*****
CALL DEFINE(A, B, D, F, NU, Q, R, N, L, M, K)
C      CALL PRINTMAT(A, 17, 17)
C      CALL PRINTMAT(B, 17, 4)
C      CALL PRINTMAT(D, 2, 17)
C      CALL PRINTMAT(F, 17, 2)
C      CALL PRINTMAT(Q, 19, 19)
C      CALL PRINTMAT(R, 2, 2)
C      CALL PRINTMAT(NU, 4, 2)
C
C      CHECK EIGENVALUES OF A
C
      CALL EGVP(A, 17, RR, RI, IND)
      WRITE(*, *) ' EIGEN OF A '
      CALL PRINTMAT(RR, 17, 1)
      CALL PRINTMAT(RI, 17, 1)

      CALL GMPRD(B, NU, BNU, 17, 4, 2)          /* FIND BNU */
      CALL SCLA(U1, 0.0, 17, 2, 0)            /* U1 = [0]17X2 */
      CALL SCLA(U2, 0.0, 2, 2, 0)             /* U2 = [0] 2X2 */

```


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```

CALL JOIN(A, U1, D, U2, N, N, L, L, A1)      /* FORM A1  */
CALL RTIE(BNU, U2, B1, N, L, O, O, L)      /* FORM B1  */
C   CALL PRINTMAT(A1, 19, 19)
C   CALL PRINTMAT(B1, 19, 2 )
C   CALL PRINTMAT(BNU, 17, 2)

CALL DEFINE_H(C1, C2, IR1, IR2)
CALL DFINEC3( C13, C23, IR13, IR23 )
WRITE(*,*) ' A-closed loop = A - B1F1C1 - B2F2C2'
WRITE(*,*) ' INPUT F1 = .... '
READ(*,*)( FF1(JJ), JJ=1, IR1)
WRITE(*,*) ' INPUT F2 = ... '
READ(*,*)( FF2(JJ), JJ=1, IR2)
WRITE(*,*) ' AREA#1 OR AREA#2 IS THE LEADER ? CHOOSE (1) OR (2) '
READ(*,*) ICHOOSE

C CHECK INITIAL GUESS
C IF ( ICHOOSE.EQ. 1 ) THEN

CALL GMPRD(FF1, C1, U1, IM1, IR1, IN)
CALL GMPRD(B1, U1, U2, IN, IM1, IN)
CALL GMSUB(A1, U2, AC, IN, IN)
CALL SINGTRAN(C23, U3, IR23, IN)
CALL GMPRD(FF2, U3, U1, IM2, IR23, IN)
CALL GMPRD(B1(1, 2), U1, U2, IN, IM2, IN)
CALL GMSUB(AC, U2, AC, IN, IN)

C ELSE
C CALL SINGTRAN(C13, U3, IR13, IN)
CALL GMPRD(FF1, U3, U1, IM1, IR13, IN)
CALL GMPRD(B1, U1, U2, IN, IM1, IN)
CALL GMSUB(A1, U2, AC, IN, IN)
CALL GMPRD(FF2, C2, U1, IM2, IR2, IN)
CALL GMPRD(B1(1, 2), U1, U2, IN, IM2, IN)
CALL GMSUB(AC, U2, AC, IN, IN)

C END IF
C CALL EGVP(AC, 19, RR, RI, IND)
DO 100 II=1, IN
WRITE(*, 101)RR(II), RI(II)
101 FORMAT(2F15. 6)
100 CONTINUE

WRITE(*,*) ' WAITING !! '
EPS = 1D-4
LIMIT = 200
CALL DBLETRAN( A1, DA, 19, 19 )
CALL DBLETRAN( B1, DB, 19, 2 )
CALL DBLETRAN( C1, DC1, IR1, IN )
CALL DBLETRAN( C2, DC2, IR2, IN )
C CALL DBLETRAN( Q, DQ, 19, 19 )
CALL DBLETRAN( FF1, DF1, IM1, IR1 )
CALL DBLETRAN( FF2, DF2, IM2, IR2 )
R1 = 1.0D0
R2 = 1.0D0
IF ( ICHOOSE.EQ. 1 ) THEN
CALL DEFINEQ(Q1, Q2)
ELSE

```

C PROGRAMME LISTING WRITTEN BY SUCHIN ARUNSAWATWONG, 12 MARCH 1988.

```

      CALL DEFINQG(Q1,Q2)
      END IF

      WRITE(*,*)'Q1 = ',Q1(8,8),Q1(9,9),Q1(17,17),Q1(18,18),Q1(19,19)
      WRITE(*,*)'Q2 = ',Q2(8,8),Q2(9,9),Q2(17,17),Q2(18,18),Q2(19,19)
      WRITE(*,*)' START RUN. .'

C      IF ( ICHOOSE.EQ.1 ) THEN
C
C      AREA # 1 IS THE LEADER AND RECEIVES MORE INFORMATION
      CALL STKOUT(DA,DB,DB(1,2),DC1,C23,Q1,Q2,R1,R2,DAC,KO,K1,L1,DF1,
&      DF2,DGRAD1,DGRAD2,J1,J2,EPS,LIMIT,IN,IM1,IM2,IR1,IR23 )
C
C      ELSE
C
C      AREA # 2 IS THE LEADER AND RECEIVES MORE INFORMATION
      CALL STKOUT(DA,DB(1,2),DB,DC2,C13,Q2,Q1,R2,R1,DAC,KO,K1,L1,DF2,
&      DF1,DGRAD2,DGRAD1,J2,J1,EPS,LIMIT,IN,IM2,IM1,IR2,IR13 )
C
C      END IF
C
C      IF ( ICHOOSE.EQ.1 ) THEN
C
C      WRITE(*,*)' AREA # 1 IS THE LEADER AND RECEIVES MORE INFORMATION'
C
C      ELSE
C
C      WRITE(*,*)' AREA # 2 IS THE LEADER AND RECEIVES MORE INFORMATION'
C
C      END IF
C
      WRITE(*,*)' KO = '
      CALL DPRINTMAT(KO,19,19)
      WRITE(*,*)' K1 = '
      CALL DPRINTMAT(K1,19,19)
      WRITE(*,*)' L1 = '
      CALL DPRINTMAT(L1,19,19 )
      WRITE(*,*)' J2 = ',J2
      WRITE(*,*)' J1 = ',J1
      WRITE(*,*)' GRAD1 = '
      CALL DPRINTMAT(DGRAD1,1,IR1 )
      WRITE(*,*)' GRAD2 = '
      CALL DPRINTMAT(DGRAD2,1,IR2 )
      WRITE(*,*)' F1 = '
      CALL DPRINTMAT(DF1,1,IR1 )
      WRITE(*,*)' F2 = '
      CALL DPRINTMAT(DF2,1,IR2 )
C
      CALL SINGTRAN(DAC,AC,19,19 )
      CALL SINGTRAN(DF1,FF1,IM1,IR1 )
      CALL SINGTRAN(DF2,FF2,IM2,IR2 )
      CALL SINGTRAN(DGRAD1,GRAD1,IM1,IR1 )
      CALL SINGTRAN(DGRAD2,GRAD2,IM2,IR2 )
      CALL EGVP(AC,19,RR,RI,IND)
      DO 200 II=1,IN
        WRITE(*,201)RR(II),RI(II)
201      FORMAT(2E17.7)
200      CONTINUE
C
      IF ( ICHOOSE.EQ.1 ) THEN

```

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```

C
      CALL GMPRD(FF1,C1,U1,IM1,IR1,IN)
      CALL GMPRD(B1,U1,U2,IN,IM1,IN)
      CALL GMSUB(A1,U2,AC,IN,IN)
C      CALL SINGTRAN(C23,U3,IR23,IN)
      CALL GMPRD(FF2,U3,U1,IM2,IR23,IN)
      CALL GMPRD(B1(1,2),U1,U2,IN,IM2,IN)
      CALL GMSUB(AC,U2,AC,IN,IN)
C
      ELSE
C
      CALL SINGTRAN(C13,U3,IR13,IN)
      CALL GMPRD(FF1,U3,U1,IM1,IR13,IN)
      CALL GMPRD(B1,U1,U2,IN,IM1,IN)
      CALL GMSUB(A1,U2,AC,IN,IN)
      CALL GMPRD(FF2,C2,U1,IM2,IR2,IN)
      CALL GMPRD(B1(1,2),U1,U2,IN,IM2,IN)
      CALL GMSUB(AC,U2,AC,IN,IN)
C
      END IF
      CALL EGVP(AC,19,RR,RI,IND)
      WRITE(*,*) ' EIGENVALUES OF A -B1F1C1 - B2F2C2 '
      DO 300 II=1,IN
        WRITE(*,301)RR(II),RI(II)
301      FORMAT(2E17.7)
300      CONTINUE

      STOP
      END

      SUBROUTINE PRINTMAT(A,IROW,ICOL)
      IMPLICIT INTEGER*2 (I-N)
      REAL*4 A(1)
      INTEGER IROW,ICOL,I,J
C
C      CAN BE USED UP TO ICOL=20
C
      DO 10 I=1,IROW
        WRITE(*,100) ( A(I+(J-1)*IROW) , J=1,ICOL )
100      FORMAT(20E14.5)
10      CONTINUE
      WRITE(*,*)
      RETURN
      END

      SUBROUTINE DPRINTMAT(A,IROW,ICOL)
      IMPLICIT INTEGER*2 (I-N)
      REAL*8 A(1)
      INTEGER IROW,ICOL,I,J
C
C      CAN BE USED UP TO ICOL=20
C
      DO 10 I=1,IROW
        WRITE(*,100) ( A(I+(J-1)*IROW) , J=1,ICOL )
100      FORMAT(20E14.5)
10      CONTINUE
      WRITE(*,*)
      RETURN
      END

```

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```

SUBROUTINE DEFINEQ ( Q1,Q2 )
REAL*8      Q1(1),Q2(1)
CALL DSCLA(Q1,ODO,19,19,0)
CALL DSCLA(Q2,ODO,19,19,0)
Q1(141)    = 1D0      /* F1  */
Q1(161)    = 0.5D0    /* Ptie */
Q1(341)    = 1D0      /* V1  */
Q2(161)    = 0.5D0    /* Ptie */
Q2(321)    = 1D0      /* F2  */
Q2(361)    = 1D0      /* V2  */
RETURN
END

```

```

SUBROUTINE DEFINQG ( Q1,Q2 )
REAL*8      Q1(1),Q2(1)
CALL DSCLA(Q1,ODO,19,19,0)
CALL DSCLA(Q2,ODO,19,19,0)
Q1(141)    = 1D0      /* F1  */
Q1(161)    = 0.5D0    /* Ptie */
Q1(341)    = 1D0      /* V1  */
Q2(161)    = 0.5D0    /* Ptie */
Q2(321)    = 1D0      /* F2  */
Q2(361)    = 1D0      /* V2  */
RETURN
END

```

```

SUBROUTINE DEFINE(A,B,D,F,NU,Q,R,N,L,M,K)
IMPLICIT INTEGER*2 (I-N)
REAL*4  A(1),B(1),D(1),F(1),NU(1),Q(1),R(1),QQ
INTEGER*2  N,L,M,K
CALL SCLA(A ,0.0,N ,N ,0)
CALL SCLA(B ,0.0,N ,M ,0)
CALL SCLA(D ,0.0,L ,N ,0)
CALL SCLA(F ,0.0,N ,K ,0)
CALL SCLA(NU,0.0,M ,L ,0)
CALL SCLA(Q ,0.0,(N+L),(N+L),0)
CALL SCLA(R ,0.0,L ,L ,0)

```

```

C
C   SET R
C
R(1) = 1
R(4) = 1

```

```

C
C   SET Q
C
QQ = 1.0
Q(141) = QQ
Q(161) = QQ
Q(321) = QQ
Q(341) = QQ
Q(361) = QQ

```

```

C
C   SET NU
C
NU(1) = 0.4
NU(2) = 0.6
NU(7) = 0.5
NU(8) = 0.5

```

C

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C SET F

C

F(5) = 0.666667
F(8) = -0.083333
F(31) = 0.666667
F(34) = -0.083333

C

C

C

SET D

D(15) = 10.0
D(17) = 1.0
D(18) = -1.0
D(34) = 10.0

C

C

C

SET B

B(1) = 4.0
B(22) = 10.0
B(44) = 4.0
B(65) = 10.0

C

C

C

SET A

A(1) = -0.2
A(2) = 4.75

A(19) = -5.0
A(20) = 0.166667
A(22) = -0.08
A(25) = 0.01

A(37) = -0.166667
A(38) = 2.0
A(39) = -0.07466
A(42) = 0.0093333

A(55) = -2.0
A(56) = -0.112
A(59) = 0.014

A(73) = -3.9944
A(74) = 0.2
A(75) = 1.31744
A(76) = -0.063194

A(90) = 10.0
A(91) = -0.5

A(107) = -0.92778
A(109) = -1.38889
A(110) = 0.115972

A(120) = -4.0
A(124) = -9.10111
A(126) = -0.27778
A(127) = -0.112361
A(128) = 22.21439

A(141) = 0.666667
A(144) = -0.083333

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```

A(150)= -0.666667
A(153)=  0.083333

A(163)= -0.2
A(164)=  4.75

A(181)= -5.0
A(182)=  0.166667
A(184)= -0.1
A(187)=  0.0125

A(199)= -0.166667
A(200)=  2.0
A(201)= -0.093334
A(204)=  0.0116625

A(217)= -2.0
A(218)= -0.14
A(221)=  0.0175

A(235)= -4.09552
A(236)=  0.2
A(237)=  1.31944
A(238)= -0.0505555

A(252)= 10.0
A(253)= -0.5

A(269)= -0.7422224
A(271)= -1.38889
A(272)=  0.092776

A(281)= -22.21439
A(282)= -4.0
A(286)= -9.107862
A(288)= -0.27778
A(289)= -0.1115167

```

```

RETURN
END

```

```

SUBROUTINE DEFINE_H(H1,H2,IR1,IR2)
IMPLICIT INTEGER*2 (I-N)
REAL*4 H1(5,19),H2(5,19)
INTEGER*2 IR1,IR2
CALL SCLA( H1,0.0,IR1,19,0 )
H1(1,2) = 0.3
H1(1,3) = 0.28
H1(1,4) = 0.42
H1(2,5) = -1.52
H1(2,7) = 2.78
H1(2,8) = 0.217
H1(3,8) = 1.0
H1(4,9) = 1.0
H1(5,18) = 1.0

```

```

C
CALL SCLA( H2,0.0,IR2,19,0 )
H2(1,11) = 0.3
H2(1,12) = 0.28
H2(1,13) = 0.42

```

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```
H2(2,14) = -1.52
H2(2,16) = 2.78
H2(2,17) = 0.217
H2(3,17) = 1.0
H2(4,9) = 1.0
H2(5,19) = 1.0
RETURN
End
```

```
SUBROUTINE DFINEC3(H1,H2,IR13,IR23)
REAL*8 H1(3,19),H2(3,19)
INTEGER*2 IR1,IR2
CALL DSCLA( H1,0.ODO,IR13,19,0 )
H1(1,8) = 1.ODO
H1(2,9) = 1.ODO
H1(3,18) = 1.ODO
```

```
C
CALL DSCLA( H2,0.ODO,IR23,19,0 )
H2(1,17) = 1.ODO
H2(2,9) = 1.ODO
H2(3,19) = 1.ODO
RETURN
End
```

```
SUBROUTINE EGVP(A,N,RR,RI,IND)
IMPLICIT INTEGER*2 (I-N)
C ***** OK. TEST ON 18 SEP. 1986 *****
DIMENSION A(1),RR(1),RI(1),C(400)
DIMENSION L1(20)
CALL MCPY(A,C,N,N,0)
CALL HSBG(N,C,N)
CALL ATEIG(N,C,RR,RI,L1,N)
RETURN
END
```

```
SUBROUTINE JOIN(A11,A12,A21,A22,N1,M1,N2,M2,A)
IMPLICIT INTEGER*2 (I-N)
REAL*4 A11(1),A12(1),A21(1),A22(1),A(1)
INTEGER*2 N1,M1,N2,M2,N,M,IA
N = N1+N2
M = M1+M2
IA = N*M1+1
CALL RTIE(A11,A21,A ,N1,M1,0,0,N2)
CALL RTIE(A12,A22,A(IA),N1,M2,0,0,N2)
RETURN
END
```

```
SUBROUTINE RCUT1(A,L,R,S,N,M,MS)
IMPLICIT INTEGER*2 (I-N)
REAL*4 A(1),R(1),S(1)
INTEGER*2 L,N,M,MS,NL
NL = N-L
DO 10 I=1,M
  DO 20 J=1,L
    R( J+(I-1)*L ) = A( J+(I-1)*N )
20  CONTINUE
  DO 30 J=1,NL
    S( J+(I-1)*NL ) = A( J+(I-1)*N+L )
30  CONTINUE
10  CONTINUE
```

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RETURN
END

SUBROUTINE DJOIN(A11, A12, A21, A22, N1, M1, N2, M2, A)
IMPLICIT INTEGER*2 (I-N)
REAL*4 A11(1), A12(1), A21(1), A22(1), A(1)
INTEGER N1, M1, N2, M2, N, M, IA
N = N1+N2
M = M1+M2
IA = N*M1+1
CALL RCUT1(A, N1, A11, A21, N, M1, 0)
CALL RCUT1(A(IA), N1, A12, A22, N, M2, 0)
RETURN
END

REAL*8 FUNCTION TR(K, N)
IMPLICIT INTEGER*2 (I-N)
REAL*8 K(1)
INTEGER*2 N, I, J
TR = K(1)
J = N+1
DO 10 I=1, (N-1)
J = J+1
TR = TR + K(J)
J = J+N
10 CONTINUE
RETURN
END

SUBROUTINE DBLETRAN(A, DA, IR, IC)
IMPLICIT INTEGER*2 (I-N)
REAL*4 A(1)
REAL*8 DA(1)
INTEGER IR, IC, I, J
I = IR*IC
DO 10 J=1, I
10 DA(J) = DBLE(A(J))
RETURN
END

SUBROUTINE SINGTRAN(DA, A, IR, IC)
IMPLICIT INTEGER*2 (I-N)
REAL*4 A(1)
REAL*8 DA(1)
INTEGER IR, IC, I, J
I = IR*IC
DO 10 J=1, I
10 A(J) = SNGL(DA(J))
RETURN
End

SUBROUTINE BTLSTW (A, X, Q, H, Y, U, N, IOPTION, IERR)
IMPLICIT INTEGER*2 (I-N)
IMPLICIT REAL*8 (A-H, O-Z)
INTEGER*2 N, IOPTION, IERR
REAL*8 A(N, N), X(N, N), Q(N, N), H(N, N), Y(N, N), U(N, N)
REAL*8 TIME1, TIME2, TTT, CTIM#A
C
C
C
C
=====

SOLVE LYAPUNOV EQUATION $AT * X + X * A + Q = 0$ (IOPTION = 0)


```

C      PROGRAMME LISTING WRITTEN BY SUCHIN ARUNSAWATWONG, 12 MARCH 1988.

C      =====
C      A*X + X*AT + I = 0 ( IOPTION = 1 )
C      A*X + X*AT + Q = 0 ( IOPTION = 2 )
C
C      IF IERR = 0 , IT DENOTES A IS STABLE AND X WILL BE COMPUTED
C      IF IERR = 999 , IT DENOTES A IS UNSTABLE AND X WILL NOT BE COMPUTED
C      ALTHOUGH THIS ROUTINE CAN SOLVE IT.
C
C      A IS NOT DESTROYED ON RETURN.
C      A, P, Q, H, HT, Y, U ARE ALL ( NXN ) REAL*8 MATRIX.
C
C      REAL*8      HNORM, EPS, AUX1(20), RR(20), RI(20), A1(16), B1(4), R1(64),
C      &          T11, T12, T21, T22, H11, H12, H21, H22, R11, R12, R21, R22
C      INTEGER*2   ID(20), K, COLUMN, ICOUNT, IS1, IS2, IROW, ICOL, K5, N4, M,
C      &          IR1, IC1
C
C      TIME1 = CTIM#A(TTT)
C
C      EPS = 1D-10
C      N4 = 4
C      IF (IOPTION.EQ.0) THEN
C          CALL DMCPY(A, H, N, N, 0)
C      ELSE
C          CALL DGMTRA(A, U, N, N)
C          CALL DMCPY(U, H, N, N, 0)
C      END IF
C
C      IS1 = 1
C      IS2 = N
C      CALL ORTHES(N, N, IS1, IS2, H, AUX1)
C      CALL ORTRAN(N, N, IS1, IS2, H, AUX1, U)
C      CALL HQRORT(N, N, IS1, IS2, H, RR, RI, U, IERR)
C
C      DO 10 K=1, N
C          IF (RR(K).GT.-1D-6) GO TO 1000
C      10 CONTINUE
C
C      NOW U CAN TRANSFORM (A)T INTO LOWER TRIANGULAR MATRIX
C
C      555 CONTINUE
C      IF ( IOPTION.EQ.0 ) THEN
C          CALL DGTPRD(A, U, Y, N, N, N)
C      ELSE
C          CALL DGMPRD(A, U, Y, N, N, N)
C      END IF
C      CALL DGTPRD(U, Y, H, N, N, N)
C
C      NOW H IS A LOWER QUASI-TRIANGULAR MATRIX.
C      THEN COMPUTE T = UT*Q*U
C
C      IF ( IOPTION.EQ.1 ) GO TO 19
C      CALL DGMPRD(Q, U, X, N, N, N)
C      CALL DGTPRD(U, X, Q, N, N, N)
C
C      FIND K AND ID(I), I=1,K
C
C      19 CONTINUE
C      HNORM = 0D0
C      DO 20 K=1, N

```

C PROGRAMME LISTING WRITTEN BY SUCHIN ARUNSAWATWONG, 12 MARCH 1988.

```

20       HNORM = HNORM + DABS(H(K,1))
C
K = 0
COLUMN = 1
DO 30 IS1=1,N
  IF (COLUMN.GE.N) GO TO 31
  K = K + 1
  IF ( DABS(H(COLUMN,COLUMN+1)).LT.DABS(EPS*HNORM) ) THEN
    ID(K) = 1
    COLUMN = COLUMN + 1
  ELSE
    ID(K) = 2
    COLUMN = COLUMN + 2
  END IF
30 CONTINUE
31 CONTINUE
  IF (COLUMN.EQ.N) THEN
    K = K + 1
    ID(K) = 1
  END IF

C SOLVE FOR Y IN   H*Y + Y*HT + T = 0
C
IROW = 1
DO 100 IS1=1,K
  ICOUNT = IS1
  ICOL = 1
  DO 99 IS2=1,ICOUNT
    IF ( ID(IS1).EQ.1 ) THEN
      IF ( ID(IS2).EQ.1 ) THEN
C
C 111111111111111111111111111111111111111111111111111111111111111111111
C  T11 = Q(IROW,ICOL)
    DO 110 M=1,(IROW-1)
      T11 = T11 + H(IROW,M)*Y(M,ICOL)
    DO 120 M=1,(ICOL-1)
      T11 = T11 + Y(IROW,M)*H(ICOL,M)
C
    Y(IROW,ICOL) = -T11/( H(IROW,IROW)+H(ICOL,ICOL) )
C
    IF (IROW.NE.ICOL) Y(ICOL,IROW) = Y(IROW,ICOL)
C 111111111111111111111111111111111111111111111111111111111111111111111
C
      ELSE
C
C 222222222222222222222222222222222222222222222222222222222222222222222
C  IC1 = ICOL + 1
    T11 = Q(IROW,ICOL)
    T12 = Q(IROW,IC1 )
    DO 130 M=1,(IROW-1)
      T22 = H(IROW,M)
      T11 = T11 + T22*Y(M,ICOL)
      T12 = T12 + T22*Y(M,IC1 )
    DO 140 M=1,(ICOL-1)
      T22 = Y(IROW,M)
      T11 = T11 + T22*H(ICOL,M)
      T12 = T12 + T22*H(IC1,M)
C
    H11 = H(IROW,IROW) + H(ICOL,ICOL)
    H12 = H(ICOL,IC1 )

```



```

C      PROGRAMME LISTING WRITTEN BY SUCHIN ARUNSAWATWONG, 12 MARCH 1988.

C      THEN FIND      X = U*Y*UT
C
C      CALL DGMTRA(U, X, N, N)
C      CALL DGMPRD(Y, X, H, N, N, N)
C      CALL DGMPRD(U, H, X, N, N, N)
C
C      IERR = 0
C
C      TIME2 = CTIM#A(TTT)
C      WRITE(*,*)' TIME USED IN BTLSTW = ', (TIME2-TIME1)
C 999  RETURN
C
C 1000 IERR = 999
C      GO TO 999
C      END

C      SUBROUTINE STKOUT( A, BO, B1, CO, C1, QO, Q1, RO, R1, AC, KO, K1, L1, FO,
C & F1, GRADO, GRAD1, JO, J1, EPS, LIMIT, IN, IMO, IM1, IRO, IR1 )
C
C      IMPLICIT INTEGER*2 (I-N)
C      INTEGER*2 LIMIT, IN, IMO, IM1, IRO, IR1
C      REAL*8     A(1), BO(1), B1(1), CO(1), C1(1), QO(1), Q1(1), RO(1), R1(1),
C & AC(1), KO(1), K1(1), L1(1), FO(1), F1(1),
C & GRADO(1), GRAD1(1), JO, J1, EPS
C
C      INTEGER*2 N, I, J, K, IK, IROW, ICOL, IGRAD, IGRADF, IFCN, ICOUNT
C      REAL*8     OLDGRAD(20), SEARCH(20), OLDFO(20), LAMBDA, SRHNORM, OLDJO,
C & MCHEPS, DMAX, DX, DX1, DPHI, GNORM
C      REAL*8     FA, FB, FC, XA, XB, XC, AA, BB, CC, DD, OLDLMD, LAMBDA1
C      REAL*8     H(20, 20), YK(20), PK(20), HYK(20)
C      REAL*8     TIME1, TIME2, TTT, CTIM#A
C      DATA      MCHEPS /7. 105428D-15/
C
C      INITIALIZE
C      I=0
C      N = IMO * IRO
C      DMAX = 0. 01D0
C
C      MCHEPS1 = 1D-8
C
C      =====
C      COMPUTE f(x) AND grad(x) AT INITIAL GUESS
C      =====
C      CALL FCNLEAD( A, BO, B1, CO, C1, QO, Q1, RO, R1, AC, KO, K1, L1, FO, F1, GRADO,
C & GRAD1, JO, J1, EPS, IN, IMO, IM1, IRO, IR1, IERR )
C      CALL GRDLEAD( A, BO, B1, CO, C1, QO, Q1, RO, R1, AC, KO, K1, L1, FO, F1, GRADO,
C & GRAD1, JO, J1, EPS, IN, IMO, IM1, IRO, IR1 )
C      WRITE(*,*)' LEADER : FOLLOWER '
C      WRITE(*,*)' JO = ', JO
C      CALL DPRINTMAT(FO, IMO, IRO)
C      WRITE(*,*)' J1 = ', J1
C      CALL DPRINTMAT(F1, IM1, IR1)
C
C      =====
C      SET h = -grad(x) AND SET H = I
C      =====
C      CONTINUE
C
C      DO 7 IROW=1,N
C        DO 5 ICOL=1,N

```

C PROGRAMME LISTING WRITTEN BY SUCHIN ARUNSAWATWONG, 12 MARCH 1988.

```

                IF (IROW.NE.ICOL) THEN
                    H(IROW,ICOL) = 0.0DO
                ELSE
                    H(IROW,ICOL) = 1.0DO
                END IF
5             CONTINUE
7             CONTINUE
C
10            DO 15 K=1,N
                SEARCH(K) = -GRADO(K)
15           CONTINUE
C
C             STORE OLD VALUES OF FO AND GRADO AND JO
C             =====
20           CONTINUE
C
C             TIME1 = CTIM*A(TTT)
C
C             DO 22 K=1,N
                OLDGRAD(K) = GRADO(K)
                OLDFO(K)   = FO(K)
22          CONTINUE
                OLDJO = JO
C
                WRITE(*,*) ' GRADIENT # 0 '
                CALL DPRINTMAT(GRADO, IMO, IRO)
C
C             =====
C             FIND STEP-SIZE OR LAMBDA
C             =====
C             FIND NORM OF SEARCH OR SRHNORM
                SRHNORM = 0.0DO
                GNORM   = 0.0DO
                DO 225 K=1,N
                    GNORM = GNORM + GRADO(K)*GRADO(K)
225                SRHNORM = SRHNORM + SEARCH(K)*SEARCH(K)
                SRHNORM = DSQRT(SRHNORM)
                GNORM   = DSQRT(GNORM)
                DO 975 K=1,N
                    IF( DABS(GRADO(K)) .LT. 1D-2 ) RETURN
975            CONTINUE
                    IF (GNORM.LT.5D-2) RETURN
C
                WRITE(*,*) ' SRHNORM = ', SRHNORM
C
C             DO 2251 K=1,N
C 2251            SEARCH(K) = SEARCH(K)/SRHNORM
C
C
C             COMPUTE DIRECTIONAL DERIVATIVE, DPHI
C             =====
                DPHI = 0.0DO
                DO 226 K=1,N
226            DPHI = DPHI + GRADO(K)*SEARCH(K)
C
C             -----
C             IF DIRECTIONAL DERIVATIVE > 0 , THEN SEARCH ALONG STEEPEST
C             DESCENT DIRECTION
C             -----
                IF (DPHI) 300,125,3

```

```

C      PROGRAMME LISTING WRITTEN BY SUCHIN ARUNSAWATWONG, 12 MARCH 1988.

300  CONTINUE
C
LAMBDA = DABS( 0.2D0*JO/DPHI )
IF ( SRHNORM.LT.1D3 ) LAMBDA = 0.2D0D/SRHNORM
IF ( SRHNORM.LT.1D-2 ) LAMBDA = 0.02D0/SRHNORM

C
C      INITIALIZE FOR FINDING BRACKET OF MIN POINT
C      =====
FA = JO
XA = 0.0D0
LAMBDA = DMAX/SRHNORM

C
C      CALCULATE JO AT THE NEXT POINT, XB
C      =====
30  CONTINUE
DO 301 K=1,N
301  FO(K) = OLDFO(K) + LAMBDA*SEARCH(K)
CALL FCNLEAD( A,BO,B1,CO,C1,QO,Q1,RO,R1,AC,KO,K1,L1,FO,F1,GRADO,
&          GRAD1,JO,J1,EPS,IN,IMO,IM1,IRO,IR1,IERR )

C
IF ( IERR.NE.0 ) THEN
LAMBDA = LAMBDA * 0.6666666666667D0
GO TO 30
END IF

C
FB = JO
XB = LAMBDA

C
IF (JO.LT.FA) GO TO 303
C
IF ( FB<FA ) THEN CONTINUE FINDING JO AT XC
C
ELSE IT DENOTES THAT THE MINIMUM HAS BEEN PASSED

XC = XB
FC = FB
3019 CONTINUE
LAMBDA = LAMBDA / 3.0D0
DO 302 K=1,N
302  FO(K) = OLDFO(K) + LAMBDA*SEARCH(K)
CALL FCNLEAD( A,BO,B1,CO,C1,QO,Q1,RO,R1,AC,KO,K1,L1,FO,F1,
&          GRADO,GRAD1,JO,J1,EPS,IN,IMO,IM1,IRO,IR1,IERR )
IF (JO.GT.FA) THEN
FC = JO
XC = LAMBDA
GO TO 3019
ELSE
XB = LAMBDA
FB = JO
END IF

C
C      NOW WE OBTAIN THE BOUND OF THE MIN. POINT
C
GO TO 329

C
303 CONTINUE
LAMBDA = LAMBDA + LAMBDA
C      NOW LAMBDA IS USED AS INTERVAL LENGTH
3031 CONTINUE
XC = XB + LAMBDA
DO 304 K=1,N
304  FO(K) = OLDFO(K) + XC*SEARCH(K)
CALL FCNLEAD( A,BO,B1,CO,C1,QO,Q1,RO,R1,AC,KO,K1,L1,FO,F1,GRADO,

```

C PROGRAMME LISTING WRITTEN BY SUCHIN ARUNSAWATWONG, 12 MARCH 1988.

```

&          GRAD1, JO, J1, EPS, IN, IMO, IM1, IRO, IR1, IERR )
IF ( IERR. NE. 0 ) THEN
    LAMBDA = LAMBDA*0.66666666666667D0
    GO TO 3031
    END IF
FC = JO
C
IF ( FC. LT. FB ) THEN      /* SEARCH FURTHER */
    FA = FB
    XA = XB
    FB = FC
    XB = XC
    GO TO 303
END IF      /* ELSE IT DENOTES THAT THE MINIMUM HAS BEEN BOUNDED */
            /* THEN PERFORM QUADRATIC INTERPOLATION */
C
=====
C QUADRATIC INTERPOLATION IS PERFORMED HERE.
C
329 CONTINUE
    ICOUNT = 0
    LAMBDA = XB
330 CONTINUE
C
    OLDLMD = LAMBDA
    AA = FA*(XB*XB-XC*XC) + FB*(XC*XC-XA*XA) + FC*(XA*XA-XB*XB)
    BB = FA*(XB-XC)      + FB*(XC-XA)      + FC*(XA-XB)
    LAMBDA = AA/BB/2D0
C
    ICOUNT = ICOUNT + 1
    DO 331 K=1, N
331    FO(K) = OLDFO(K) + LAMBDA*SEARCH(K)
    CALL FCNLEAD( A, B0, B1, C0, C1, Q0, Q1, R0, R1, AC, KO, K1, L1, F0, F1, GRAD0,
&          GRAD1, JO, J1, EPS, IN, IMO, IM1, IRO, IR1, IERR )
C
    IF ( LAMBDA. GT. XB ) THEN
        IF ( JO. LT. FB ) THEN
            XA = XB
            FA = FB
            XB = LAMBDA
            FB = JO
        ELSE
            XC = LAMBDA
            FC = JO
        END IF
    ELSE IF ( JO. LT. FB ) THEN
        XC = XB
        FC = FB
        XB = LAMBDA
        FB = JO
    ELSE
        XA = LAMBDA
        FA = JO
    END IF
C
IF ( DABS(OLDLMD-LAMBDA). LT. DABS(5D-4*OLDLMD) ) GO TO 400
IF ( DABS(FA-FB). LT. DABS(1D-10*FB) ) GO TO 400
IF ( DABS(FB-FC). LT. DABS(1D-10*FB) ) GO TO 400
IF ( ICOUNT. GE. 5 ) GO TO 400
C
C REDUCE THE INTERVAL IN CASE OF UNBALANCED INTERVAL

```


C PROGRAMME LISTING WRITTEN BY SUCHIN ARUNSAWATWONG, 12 MARCH 1988.

C SO AS TO REDUCE THE COMPUTATION IN QUADRATIC INTERPOLATION
C PROCESS

IF (DABS(XB-XA) .GT. DABS(O.1DO*(XC-XB))) GO TO 330

IF (DABS(XC-XB) .GT. DABS(O.1DO*(XB-XA))) GO TO 330

IF (DABS(XB-XA) .LT. DABS(XC-XB)) THEN

C =====
C XC-XB IS VERY MUCH LARGER THAN XB-XA
C =====

LAMBDA1 = XB + O.3DO*(XC-XB)

3099 CONTINUE

C DO 3001 K=1,N

3001 FO(K) = OLDFO(K) + LAMBDA1*SEARCH(K)

CALL FCNLEAD(A, BO, B1, CO, C1, GO, Q1, RO, R1, AC, KO, K1, L1, FO,
& F1, GRADO, GRAD1, JO, J1, EPS, IN, IMO, IM1, IRO, IR1, IERR)

C IF (JO .GT. FB) THEN

XC = LAMBDA1

FC = JO

ELSE

XA = XB

FA = FB

XB = LAMBDA1

FB = JO

END IF

ELSE

3098 LAMBDA1 = XB - O.3DO*(XB-XA)

C CONTINUE

C DO 3002 K=1,N

3002 FO(K) = OLDFO(K) + LAMBDA1*SEARCH(K)

CALL FCNLEAD(A, BO, B1, CO, C1, GO, Q1, RO, R1, AC, KO, K1, L1, FO,
& F1, GRADO, GRAD1, JO, J1, EPS, IN, IMO, IM1, IRO, IR1, IERR)

C IF (JO .GT. FB) THEN

XA = LAMBDA1

FA = JO

ELSE

XC = XB

FC = FB

XB = LAMBDA1

FB = JO

END IF

END IF

GO TO 330

C HAVING TERMINATED FROM LINE SEARCH PROCESS

C =====

400 CONTINUE

C -----
C SELECT WHICH IS MINIMUM AMONG THREE POINTS, THEN EXIT LINE-SEARCH
C -----

IF (FA .GT. FB) THEN

LAMBDA = XB

JO = FB

ELSE

LAMBDA = XA

JO = FA

END IF

IF (FC .LT. JO) THEN

C PROGRAMME LISTING WRITTEN BY SUCHIN ARUNSAWATWONG, 12 MARCH 1988.

```

          .LAMBDA = XC
          JO = FC
      END IF
C -----
C UPDATE VECTOR
C -----
      DO 409 K=1,N
409      FO(K) = OLDFO(K) + LAMBDA*SEARCH(K)
C -----
C CHECK TERMINATION , USING THE GIVEN MACHINE EPS
C -----
      IF ( DABS(JO).LT.1D-5 ) GO TO 119
          IF ( DABS(JO-OLDJO).LT.DABS(OLDJO*MCHEPS) ) GO TO 125
119      CONTINUE
          DO 120 K=1,N
              DX = DABS( OLDFO(K)-FO(K) )
              DX1 = DABS( OLDFO(K) )*EPS + MCHEPS
              IF ( DX.GT.DX1 ) GO TO 130
120      CONTINUE
C*****
125      RETURN
C*****
130      I = I+1
C
      TIME2 = CTIM#A(TTT)
      WRITE(*,*)' TIME USED IN THIS ITERATION = ',(TIME2-TIME1)
      ITER = I
C
      WRITE(*,*)'*****'
      WRITE(*,116)I
116      FORMAT(' I = ',I5)
          WRITE(*,*)' LAMBDA =',LAMBDA
          WRITE(*,*)' JO = ',JO
          CALL DPRINTMAT(FO,IMO,IRO)
          WRITE(*,*)' J1 = ',J1
          CALL DPRINTMAT(F1,IM1,IR1)
          WRITE(*,*)'*****'
C
      IF (I.GT.LIMIT) GO TO 999
C
C CALCULATE THE GRADIENT OF THE NEXT POINT
C
      CALL GRDLEAD( A,BO,B1,CO,C1,QO,Q1,RO,R1,AG,KO,K1,L1,FO,F1,GRADG,
&                GRAD1,JO,J1,EPS,IN,IMO,IM1,IRO,IR1 )
C -----
C UPDATE METRIC MATRIX
C -----
      DO 773 K=1,N
          YK(K) = GRADG(K) - OLDGRAD(K)
          PK(K) = FO(K) - OLDFO(K)
773      CONTINUE
C
      DO 775 IK=1,N
          HYK(IK) = 0.0D0
          DO 774 K=1,N
              HYK(IK) = HYK(IK) + H(IK,K)*YK(K)
774      CONTINUE
775      CONTINUE
C
      DX = 0.0D0

```

C PROGRAMME LISTING WRITTEN BY SUCHIN ARUNSAWATWONG, 12 MARCH 1988.

```

DX1 = 0.0D0
DO 776 K=1,N
  DX = DX + HYK(K) * YK(K)
  DX1 = DX1 + PK(K) * YK(K)
776 CONTINUE
C
DO 800 IK=1,N
  DO 801 K=1,N
    H(IK,K) = H(IK,K) + PK(IK)*PK(K)/DX1 - HYK(IK)*HYK(K)/DX
801 CONTINUE
800 CONTINUE
C
C SET SEARCH DIRECTION FOR THE NEXT ITERATION
C =====
DO 803 K=1,N
  SEARCH(K) = 0.0D0
  DO 802 IK=1,N
    SEARCH(K) = SEARCH(K) - H(K,IK) * GRADO(IK)
802 CONTINUE
803 CONTINUE
GO TO 20
C
999 WRITE(*,*) ' THE ITERATIONS CANNOT CONVERGE IN LIMIT. '
RETURN
End

SUBROUTINE FCNLEAD ( A, BO, B1, CO, C1, GO, Q1, RO, R1, AC, KO, K1, L1, FO, F1,
% GRADO, GRAD1, JO, J1, EPS, IN, IMO, IM1, IRO, IR1, IERR )
IMPLICIT INTEGER*2 (I-N)
INTEGER*2 IN, IMO, IM1, IRO, IR1, IERR
REAL*8 A(1), BO(1), B1(1), CO(1), C1(1), GO(1), Q1(1), RO(1), R1(1),
% AC(1), KO(1), K1(1), L1(1), FO(1), F1(1),
% GRADO(1), GRAD1(1), JO, J1, EPS
INTEGER*2 ITMAX, ITER, NO, N1, IW
REAL*8 AA(361), U(361), V(361), HH(361), EPS1, HDIFF, BUFFER,
% F1BUFFER(10), J1BUFFER, JOFRNT, JOBACK, MEPS
REAL*8 TR, DMAX1, DMIN1
DATA MEPS /7.0D-14/
C
C+++++
C START TO FIND OPTIMAL REACTION DUE TO FO
C+++++
C
C COMPUTE AA = A - BO_FO_GO
C
CALL DGMPRD(FO, CO, U, IMO, IRO, IN) /* U = FO_CO */
CALL DGMPRD(BO, U, V, IN, IMO, IN) /* V = BO_FO_GO */
CALL DGMSUB(A, V, AA, IN, IN)
C
EPS1 = EPS * 0.01D0
ITMAX = 100
CALL DFP( F1, J1, GRAD1, EPS1, ITMAX, AA, B1, C1, K1, L1, AC, Q1, R1,
% IN, IM1, IR1, ITER, IERR )
IF (IERR.NE.0) GO TO 990
C
DO 444 IW=1, IR1
C 444 WRITE(*,*) ' GRAD = ', GRAD1(IW)
C CALL DPRINTMAT(AC, IN, IN)
C

```

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C      PROGRAMME LISTING WRITTEN BY SUCHIN ARUNSAWATWONG, 12 MARCH 1988.

C      COMPUTE V = ( QO + CO'FO'RO_FO_CO )
C
C      CALL DGMPRD(RO,U,V,IMO,IMO,IN)      /* V = RO_FO_CO          **/
C      CALL DGTPRD(FO,V,U,IMO,IRO,IN)     /* U = FO'RO_FO_CO      **/
C      CALL DGTPRD(CO,U,V,IRO,IN,IN)      /* V = CO'FO'RO_FO_CO   **/
C      CALL DGMADD(QO,V,V,IN,IN)          /* V = QO +CO'FO'RO_FO_CO **/

C      CALL DPRINTMAT(V,IN,IN)
C      ITMAX = 30
C      CALL DMCPY( AC,U,IN,IN,0 )
C      CALL DLYAP( U,V,KO,1.ODO,1.OD-14,IN,ITMAX,0 )

CALL BTLSTW(AC,KO,V,HH,AA,U,IN,0,IERR)
JO = TR(KO,IN)*0.5DO

C
990 RETURN
END

SUBROUTINE GRDLEAD ( A,BO,B1,CO,C1,QO,Q1,RO,R1,AC,KO,K1,L1,FO,F1,
& GRADO,GRAD1,JO,J1,EPS,IN,IMO,IM1,IRO,IR1 )
IMPLICIT INTEGER*2 (I-N)
INTEGER*2 IN,IMO,IM1,IRO,IR1
REAL*8 A(1),BO(1),B1(1),CO(1),C1(1),QO(1),Q1(1),RO(1),R1(1),
& AC(1),KO(1),K1(1),L1(1),FO(1),F1(1),
& GRADO(1),GRAD1(1),JO,J1,EPS
INTEGER*2 I,J,NO,N1,IERR1
REAL*8 HDIFF,BUFFER,F1BUFFER(10),J1BUFFER,JOFRNT,JOBACK,MEPS
REAL*8 TR,DMAX1,DMIN1
DATA MEPS /7.OD-14/

C      HDIFF = DMAX1( DMIN1(((3*JO*MEPS)**(1DO/3DO)),1D-3) , 2D-5 )
NO = IMO * IRO
N1 = IM1 * IR1
DO 250 I=1,NO
  BUFFER = FO(I)

C      FO(I) = BUFFER + HDIFF
DO 150 J=1,N1
  F1BUFFER(J) = F1(J)
  CALL FCNLEAD( A,BO,B1,CO,C1,QO,Q1,RO,R1,AC,KO,K1,L1,FO,
& F1BUFFER,GRADO,GRAD1,JOFRNT,J1BUFFER,EPS,IN,IMO,
& IM1,IRO,IR1,IERR1 )
  FO(I) = BUFFER - HDIFF
DO 160 J=1,N1
  F1BUFFER(J) = F1(J)
  CALL FCNLEAD( A,BO,B1,CO,C1,QO,Q1,RO,R1,AC,KO,K1,L1,FO,
& F1BUFFER,GRADO,GRAD1,JOBACK,J1BUFFER,EPS,IN,IMO,
& IM1,IRO,IR1,IERR1 )
  GRADO(I) = ( JOFRNT-JOBACK )/( 2.ODO*HDIFF )

C      FO(I) = BUFFER
250 CONTINUE
C
990 RETURN
END

SUBROUTINE FUNCT( F,VAL,GRAD,
& A1,B1,C,DK,DL,AC,Q,R,IN,IM,IR,IERR )
C
C      A1,B1,C,DK,DL,AC,Q,R,IN,IM,IR )

```

C PROGRAMME LISTING WRITTEN BY SUCHIN ARUNSAWATWONG, 12 MARCH 1988.

```

C
  IMPLICIT INTEGER*2 (I-N)
  REAL*8  F(1), VAL, GRAD(1), A1(1), B1(1), C(1), DK(1), DL(1), AC(1), Q(1),
  &      R(1), TR
  INTEGER*2  IN, IM, IR, IERR
  REAL*8     U(361), V(361), HH(361), YY(361)

C
C     INTEGER*2  IN, IM, IR,     IND, ITER
C     REAL*8     U(400), V(400), RR(20), RI(20), UV(400)
C=====
CCC     COMMON /OUT/ A1(19, 19), B1(19, 2), C(5, 19), DK(19, 19), DL(19, 19),
C     &      AC(19, 19), Q(19, 19), R(2, 2),     IN, IM, IR
C=====
C
C     COMPUTE AC = A-BFC
C
C     CALL DGMPRD(F, C, U, IM, IR, IN)
C     CALL DGMPRD(B1, U, V, IN, IM, IN)           /* V = BFC */
C     CALL DGMSUB(A1, V, AC, IN, IN)

C
C     COMPUTE V = ( Q+C'F'RFC )
C
C     CALL DGMPRD(R, U, V, IM, IM, IN)           /* V = RFC */
C     CALL DGTPRD(F, V, U, IM, IR, IN)           /* U = F'RFC */
C     CALL DGTPRD(C, U, V, IR, IN, IN)           /* V = C'F'RFC */
C     CALL DGMADD(Q, V, V, IN, IN)               /* V = Q+C'F'RFC */

C *****
C     SOLVE TWO LYAPUNOV'S EQUATIONS.
C *****
C     CALL DMCPY(AC, UV, IN, IN, 0)
C     ITER = 30
C     CALL DLYAP(UV, V, DK, 1. ODO, 1. OD-14, IN, ITER, 0)
C     CALL DMCPY(AC, UV, IN, IN, 0)
C     CALL DLYAP(UV, U, DL, 1. ODO, 1. OD-14, IN, ITER, 1)
C
C     CALL BTLSTW(AC, DK, V, HH, YY, U, IN, 0, IERR)
C     IF (IERR.NE.0) GO TO 1000
C     VAL = TR(DK, IN)*0.5DO
C     =====
C     CALCULATE GRADIENT
C     GRAD = RFCLC'-B'KLC'
C     =====
C
C     COMPUTE U = I
C
C     CALL DSCLA(V, 0. ODO, IN, IN, 0)
C     CALL DDCLA(V, 1. ODO, IN, 0)
C     CALL BTLSTW(AC, DL, V, HH, YY, U, IN, 1, IERR)
C
C     CALL DGMTRA(C, U, IR, IN)                   /* U = C' */
C     CALL DGMPRD(DL, U, V, IN, IN, IR)           /* V = LG' */
C     CALL DGMPRD(C, V, U, IR, IN, IR)           /* U = CLG' */
C     CALL DGMPRD(F, U, V, IM, IR, IR)           /* V = FCLG' */
C     CALL DGMPRD(R, V, GRAD, IM, IM, IR)         /* GRAD = RFCLG' */
C     CALL DGMTRA(C, U, IR, IN)                   /* U = C' */
C     CALL DGMPRD(DL, U, V, IN, IN, IR)           /* V = LG' */
C     CALL DGMPRD(DK, V, U, IN, IN, IR)           /* U = KLC' */
C     CALL DGTPRD(B1, U, V, IN, IM, IR)           /* V = B'KLC' */
C     CALL DGMSUB(GRAD, V, GRAD, IM, IR)         /* GRAD = RFCLG'-B'KLC' */

```

C PROGRAMME LISTING WRITTEN BY SUCHIN ARUNSAWATWONG, 12 MARCH 1988.

```

998 RETURN
C-----
999 WRITE(*,*) ' THE SYSTEM IS NOT STABLE!! '
1000 RETURN
C-----
      END

      SUBROUTINE DFP( X, FX, GRAD, EPS, LIMIT,
&                  A1, B1, C, DK, DL, AC, Q, R, IN, IM, IR, ITER, IERR )
C      &
&                  A1, B1, C, DK, DL, AC, Q, R, IN, IM, IR, ITER )
      IMPLICIT INTEGER*2 (I-N)
      REAL*8      X(1), GRAD(1), FX, EPS, A1(1), B1(1), C(1), DK(1), DL(1), AC(1),
&                Q(1), R(1)
&                LIMIT, IN, IM, IR, ITER, IERR
      INTEGER*2   N, I, J, K, IK
      REAL*8      GRADO(20), SEARCH(20), XQ(20), LAMBDA, SRHNORM, GAMMA, DX,
&                GNORM, FA, FB, XA, XB, DPHIA, DPHIB, DPHI, Z, W, MU, DMAX, DX1,
&                H(20, 20), YK(20), PK(20), HYK(20), FOLD, MEPS
      DATA      MEPS /7.105428D-15/
C=====
C      REAL*8      A1, B1, C, DK, DL, AC, Q, R, IN, IM, IR
C      COMMON /OUT/ A1(19, 19), B1(19, 2), C(5, 19), DK(19, 19), DL(19, 19),
C      &            AC(19, 19), Q(19, 19), R(2, 2),      IN, IM, IR
C=====
C
C      INITIALIZE
      I = 0
      ITER = 0
      N = IM * IR
      DMAX = 0.01DO
C=====
C      COMPUTE f(x) AND grad(x) AT INITIAL GUESS
C=====
      CALL FUNCT(X, FX, GRAD, A1, B1, C, DK, DL, AC, Q, R, IN, IM, IR, IERR)
C
      IF ITER=0 AND IERR<>0 , IT DENOTES THE INITIAL GUESS IS NOT A.S.
C
      IF (IERR.NE.0) GO TO 1000

      CALL DPRINTMAT(X, IM, IR)
      WRITE(*,*) ' J = ', FX
C=====
C      SET h = -grad(x) AND SET H = I
C=====
3      CONTINUE

      DO 7 IROW=1, N
        DO 5 ICOL=1, N
          IF (IROW.NE.ICOL) THEN
            H(IROW, ICOL) = 0.0DO
          ELSE
            H(IROW, ICOL) = 1.0DO
          END IF
6          CONTINUE
7          CONTINUE
C
10         DO 15 K=1, N
            SEARCH(K) = -GRAD(K)
15         CONTINUE

```

```

C      PROGRAMME LISTING WRITTEN BY SUCHIN ARUNSAWATWONG, 12 MARCH 1988.

C
C      STORE OLD VALUES OF X AND GRAD AND FX
C      =====
20    CONTINUE
      DO 22 K=1,N
        GRAD(K) = GRAD(K)
        XO(K) = X(K)
22    CONTINUE
      FOLD = FX
C=====
C      FIND STEP-SIZE OR LAMBDA
C=====
C      FIND NORM OF SEARCH OR SRHNORM
      SRHNORM = 0.0D0
      DO 225 K=1,N
225   SRHNORM = SRHNORM + SEARCH(K)*SEARCH(K)
      SRHNORM = DSQRT(SRHNORM)

C      COMPUTE DIRECTIONAL DERIVATIVE, DPHIA
      DPHIA = 0.0D0
      DO 226 K=1,N
226   DPHIA = DPHIA + GRAD(K)*SEARCH(K)

C
C      IF DIRECTIONAL DERIVATIVE > 0 , THEN SEARCH ALONG STEEPEST
C      DESCENT DIRECTION
C
      IF (DPHIA) 300,125,3
300   CONTINUE
C
      IF (I.GT.3) DMAX = 0.1D0
      IF (SRHNORM.LT.1D-3) DMAX = 0.01D0
C
      LAMBDA = DABS(0.2D0*FX/DPHIA)
      IF (SRHNORM.LT.1D3 ) LAMBDA = 0.4D0 /SRHNORM
      IF (SRHNORM.LT.1D-2) LAMBDA = 0.02D0/SRHNORM
C
      FA = FX
      XA = 0.0D0
C
      LAMBDA = DMAX/SRHNORM
C
30   CONTINUE
      DO 301 K=1,N
301   X(K) = XO(K) + LAMBDA*SEARCH(K)
      CALL FUNCT(X,FX,GRAD,A1,B1,C,DK,DL,AC,G,R,IN,IM,IR,IERR)
      IF (IERR.NE.0) THEN
        LAMBDA = LAMBDA*0.666666666666667D0
        GO TO 30
      END IF
C
C      COMPUTE DPHIB, THE DIRECTIONAL DERIVATIVE AT THE NEW POINT
      DPHIB = 0.0D0
      DO 302 K=1,N
302   DPHIB = DPHIB + GRAD(K)*SEARCH(K)
C      CHECK WHETHER THE MINIMUM HAS BEEN BOUNDED OR NOT
      IF (DPHIB) 310,400,320
310   DPHIA = DPHIB
        XA = LAMBDA
        FA = FX

```

C PROGRAMME LISTING WRITTEN BY SUCHIN ARUNSAWATWONG, 12 MARCH 1988.

```

          LAMBDA = LAMBDA + LAMBDA
          GO TO 30
320   XB = LAMBDA
      FB = FX
C
C       CUBIC INTERPOLATION IS PERFORMED HERE.
C
          ICOUNT = 0
330   Z = 3*(FA-FB)/(XB-XA) + DPHIA + DPHIB
      W = DSQRT( Z*Z - DPHIA*DPHIB )
      MU = ( DPHIB + W - Z )/( DPHIB - DPHIA + 2*W )
      ICOUNT = ICOUNT + 1
      LAMBDA = XB - MU*(XB-XA)
C
          WRITE(*,555)XA,FA,XB,FB
C 555   FORMAT('XA FA , XB,FB' , 4E15.6)
C
          DO 331 K=1,N
331   X(K) = XO(K) + LAMBDA*SEARCH(K)
      CALL FUNCT(X,FX,GRAD,A1,B1,C,DK,DL,AC,G,R,IN,IM,IR,IERR)
      DPHI = 0.ODO
      DO 332 K=1,N
332   DPHI = DPHI + GRAD(K)*SEARCH(K)
C
          WRITE(*,777) DPHI,LAMBDA
C 777   FORMAT(' DPHI = ',2E15.6)
C
C       CHECK WHETHER THE MINIMUM IS CLOSED ENOUGH OR NOT
C       IF ( DABS(DPHI/SRHNORM).LT.1D-3 ) GO TO 400
C       IF ( ICOUNT.GE.4 ) GO TO 400
C       IF ( DPHI.LT.0.ODO ) GO TO 334
333   XB = LAMBDA
      FB = FX
      DPHIB = DPHI
      GO TO 330
334   XA = LAMBDA
      FA = FX
      DPHIA = DPHI
      GO TO 330
C
C       HAVING TERMINATED FROM LINE SEARCH PROCESS
C       =====
400   CONTINUE
C
C       CHECK TERMINATION ; USING THE GIVEN MACHINE EPS
C       IF ( DABS(FX).LT.1D-5 ) GO TO 119
C       IF ( DABS(FX-FOLD).LT.DABS(FOLD*MEPS) ) GO TO 125
119   CONTINUE
      DO 120 K=1,N
          DX = DABS( XO (K)-X(K) )
          DX1 = DABS(XO(K))*EPS + MEPS
          IF ( DX.GT.DX1 ) GO TO 130
120   CONTINUE
C*****
125   RETURN
C*****
130   I = I+1
      ITER = I
C       WRITE(*,116)I

```


C PROGRAMME LISTING WRITTEN BY SUCHIN ARUNSAWATWONG, 12 MARCH 1988.

```

C116     FORMAT(' I = ', I8)
C        CALL DPRINTMAT(X, IM, IR)
C        WRITE(*,*) ' J = ', FX

           IF (I.GT.LIMIT) GO TO 999
C -----
C        UPDATE METRIC MATRIX
C -----
           DO 773 K=1,N
             YK(K) = GRAD(K) - GRADO(K)
             PK(K) = X(K) - XO(K)
773      CONTINUE
C
           DO 775 IK=1,N
             HYK(IK) = 0.0DO
             DO 774 K=1,N
               HYK(IK) = HYK(IK) + H(IK,K)*YK(K)
774      CONTINUE
775      CONTINUE
C
           DX = 0.0DO
           DX1 = 0.0DO
           DO 776 K=1,N
             DX = DX + HYK(K) * YK(K)
             DX1 = DX1 + PK(K) * YK(K)
776      CONTINUE
C
           DO 800 IK=1,N
             DO 801 K=1,N
               H(IK,K) = H(IK,K) + PK(IK)*PK(K)/DX1 - HYK(IK)*HYK(K)/DX
801      CONTINUE
800      CONTINUE
C
C        SET SEARCH DIRECTION
C        =====
           DO 803 K=1,N
             SEARCH(K) = 0.0DO
             DO 802 IK=1,N
               SEARCH(K) = SEARCH(K) - H(K,IK) * GRAD(IK)
802      CONTINUE
803      CONTINUE
           GO TO 20
C
999      WRITE(*,*) ' THE ITERATIONS CANNOT CONVERGE IN LIMIT. '
1000     RETURN
           END

```

ประวัติผู้เขียน

นาย สุชิน อรุณสวัสดิ์วงศ์ เกิดวันที่ 6 มกราคม พ.ศ. 2506 ที่กรุงเทพมหานคร สำเร็จปริญญาวิศวกรรมศาสตรบัณฑิต สาขาวิศวกรรมไฟฟ้า จากจุฬาลงกรณ์มหาวิทยาลัย เมื่อปี พ.ศ. 2527 หลังจากนั้นได้เข้าศึกษาต่อปริญญาโทในภาควิศวกรรมไฟฟ้า สาขาระบบควบคุม ที่จุฬาลงกรณ์มหาวิทยาลัย ระหว่างปีการศึกษา 2528 ถึง 2529 ได้ทำหน้าที่เป็นทั้งผู้ช่วยสอน และผู้ช่วยวิจัยของห้อง วิจัยระบบควบคุม ภาควิศวกรรมไฟฟ้า

